

TUTORIAL







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Tutorial



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1 Introduction

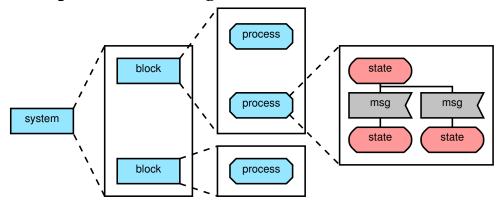
Before starting this tutorial, it is important to understand the basic concepts used in PragmaDev Studio. These concepts derive from the two languages supported by PragmaDev Studio, SDL and SDL-RT:

- SDL stands for Specification and Description Language. SDL is a graphical, objectoriented, formal language defined by the International Telecommunication Union-Telecommunication Standardization Sector (ITU-T) as recommendation Z100. The language is intended for the specification of complex, event-driven, real-time and interactive applications involving many concurrent activities that communicate using discrete signals.
- SDL-RT stands for Specification and Description Language Real Time. It is a mix of SDL with another graphical language, UML, and of a textual language, C. It retains the graphical abstraction brought by SDL while keeping the precision of traditional techniques in real-time and embedded software development and making simpler the re-use of legacy code by using natively the C language. The object-orientation is also pushed a step further by using the UML diagrams.

The underlying concepts of both languages are the same: the overall application to develop is called the system. Anything that is outside the system is called the **environment**. The system itself is described via four complementary and consistent views:

Architecture

A **system** can be decomposed in functional **blocks**. A **block** can be further decomposed in sub-**blocks** and so on until the functionality of the final **blocks** are simple enough. A block then fulfils its functionality with one or more **processes**, communicating with each other via messages (also called signals). A **process** is basically a task and has an implicit message queue to receive messages from other tasks. There is no need to define it. A block has no direct implementation in the final application; it is a matter of organizing and structuring the application. **Blocks** and **process** are called **agents**.



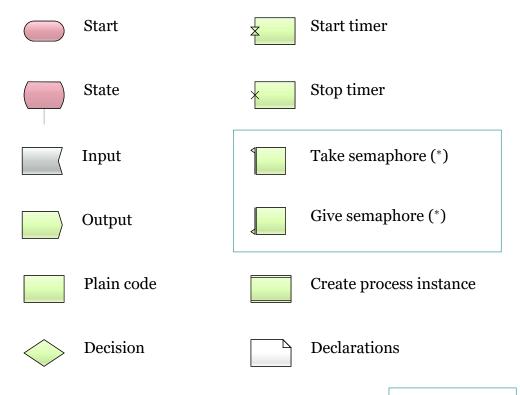


• Communication

Agents exchange messages through channels. Messages going through channels are listed to define the interface between the **agents**. When it comes to final code on the target, channels have no direct implementation; they are only used for structuring the software and defining the interfaces.

Behavior

A process behavior is described graphically as a finite state machine. Internal process states, events (messages), decisions, timer manipulations, semaphore manipulations have specific symbols briefly summarized below necessary to understand the following tutorial:



(*) SDL-RT only

SDL or SDL-RT procedures can be called within the process behavior description. In SDL-RT, C functions can be called as well; SDL also allows the call of C function via external operators or procedures.

• Data and syntax

This is where SDL and SDL-RT differ the most:

- In SDL, data is defined via ADT (Abstract Data Types), using specific concepts and notations. The data manipulation has also a specific syntax, derived from languages such as Pascal.
- In SDL-RT, the C language is used to define and manipulate data, making things more familiar to developers.

Another SDL-RT specificity is the integration of UML use case and class diagrams for less time-critical parts of the system. Objects can be associated to processes or blocks



and used in the behavioral parts of the processes.

In both SDL and SDL-RT models, PragmaDev Studio also integrates the Message Sequence Chart dynamic view. On such a diagram, time flows from top to bottom. Lifelines represent agents, semaphores or objects and key events are represented. The diagram emphasizes the sequence in which the events occur.

The two languages have each their specific domain of usage:

- SDL will be mainly used during the specification phase. Being formal, it also allows more possibilities of verification and testing.
- SDL-RT will be mainly used in the development phase, since it is closer to the hardware on which the software will eventually run.

In addition to the full features PragmaDev Studio, there are also two variants of the tool that focus on each of this languages: PragmaDev Specifier for SDL modelling, and PragmaDev Developer for SDL-RT modeling.

Would you need any extra information on the diagrams and their meaning, the following references may be used:

- For SDL, the SDL Forum web-site has many tutorials and presentations: http://www.sdl-forum.org/
- For SDL-RT, the reference manual is available in PragmaDev Studio via the *Help* / SDL-RT reference menu. This manual is also available on the SDL-RT web-site: http://www.sdlrt.org



2 A simple system

The system we have chosen is simple enough to be written from scratch but rich enough to pinpoint the basics of SDL-RT and SDL. It is a very basic phone system composed of a central and of several phones. When the phones are created, the central gives them an automatically computed phone number. When a user takes a phone to call another one, the phone asks the central the id of the phone to be called identified by its phone number. The caller sends directly a call request to the distant phone. For simplicity sake the distant phone automatically answers.

This tutorial is divided into two parts, depending on the tool you will be using, or on the modelling language if you're using PragmaDev Studio:

- The tutorial for PragmaDev Specifier describes SDL modelling and starts on page 8.
- The tutorial for PragmaDev Developer describes SDL-RT modelling and starts on page 71.

The last part of this tutorial describes the automatic documentation generation (page 122). It is based on the SDL system but that can be applied to the SDL-RT example, and therefore will work in both variants of the tool.

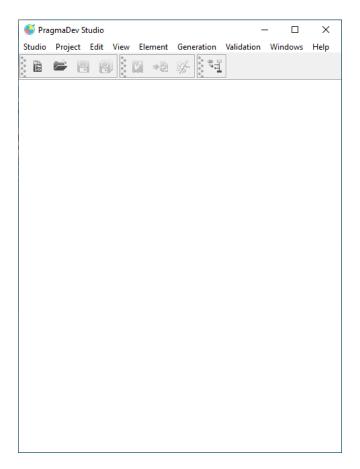
If you do not want to design the example, you can find a complete project of this system in the examples under "Specifier/Tutorial" and 'Developer/Tutorial'.



3 PragmaDev Specifier Tutorial

3.1 Organization

Let's get our hands on the tool! Start *PragmaDev Specifier* (or *PragmaDev Studio* if this will be the application you will be using). The window that appears is called the Project manager:

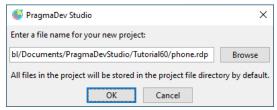


The Project manager window

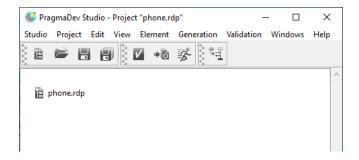
The project manager gathers all the files needed in the project. First let's create a new project with the $New\ project$ button:



A window will pop up to set the project file name. Use the 'Browse' button to select the project's parent folder and name it "phone":



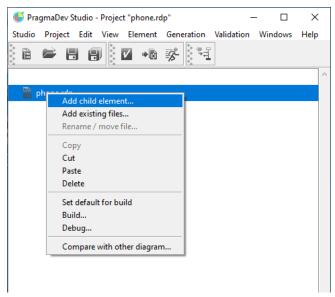
Click OK to create the project and open it:



Phone empty project

3.2 Requirements

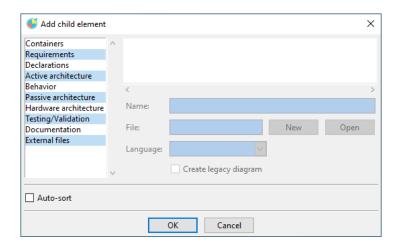
Let us express the requirements of our system with a Message Sequence Chart (MSC). To add an MSC, select the project, and click on the right mouse button. A contextual menu will appear:



Add components to the project

Select *Add child element* and the following window will appear:





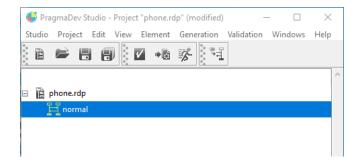
The add component window

In *Requirements*, select *MSC* element and click on the *New* button. Go to the directory where your project is and type in "normal" with no extension. Click on save and you will get the following window:



Completed Add component window

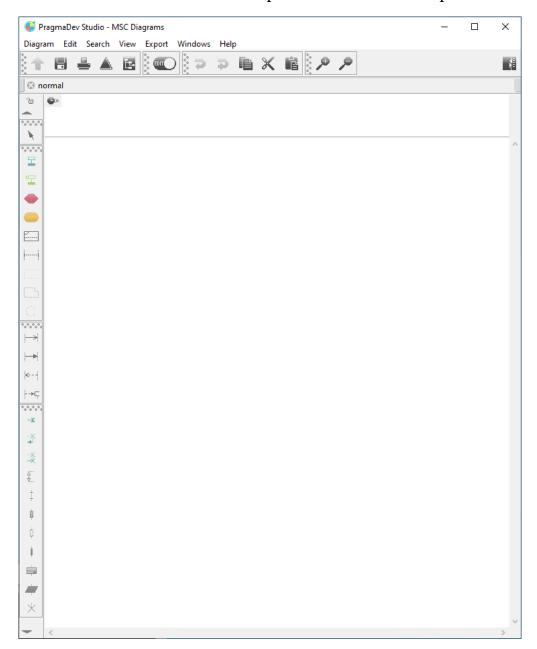
Click Ok and the "normal" MSC appears in the "phone" project:



"normal" MSC in "phone" project



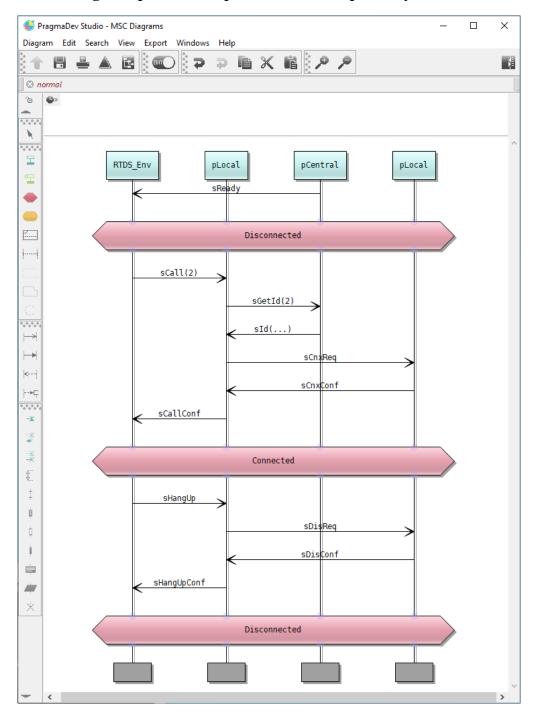
Double click on the MSC name or icon to open it. The MSC editor opens:



The MSC editor



Draw the following to express the requirements of our phone system:



The "normal" MSC

You will have to use the tool bar on the left. If you have any problem refer to the user's manual.

This MSC basically says the following:

- pCentral indicates the system has been initialized and is ready
- The initial global state is Disconnected

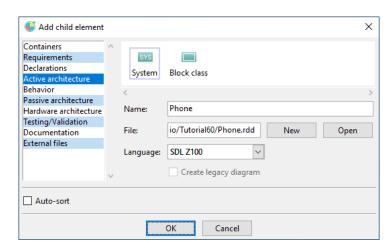


- The user represented as the environment (RTDS_Env) makes a request on the first phone pLocal to call the phone with the number 2
- The first pLocal asks the central the queue id of the phone with number 2
- The first pLocal uses the id to send a connect request (sCnxReq) to the second pLocal
- The second pLocal being disconnected, it confirms the connection (sCnxConf)
- The first pLocal tells the environment the call has succeeded
- The global system state is then considered Connected
- The user hangs up
- The first pLocal sends a disconnection request (sDisReq) to the second pLocal
- The second pLocal confirms disconnection (sDisConf) back to the first pLocal
- The first pLocal tells the environment the disconnection is confirmed
- The overall final state is back to Disconnected

You can write some other MSCs to get clearer ideas on what you want to do. Note the instances represented on the MSC can be any type of agent. Somehow you are roughly defining the first architectural elements. You can copy from the SDL/Tutorial example the "normal" and "busy" MSCs in the project to complete the description.

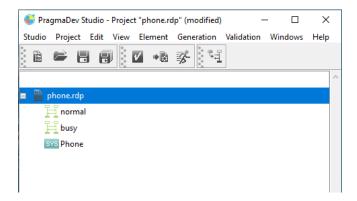
3.3 Design

Let us now specify and design the system. As for creating an MSC, select *Add child element* on the project, then the *Active architecture* category in the dialog, and select *System* component. Note that the dialog will this time require to set a modelling language for the diagram. Choose SDL Z100:



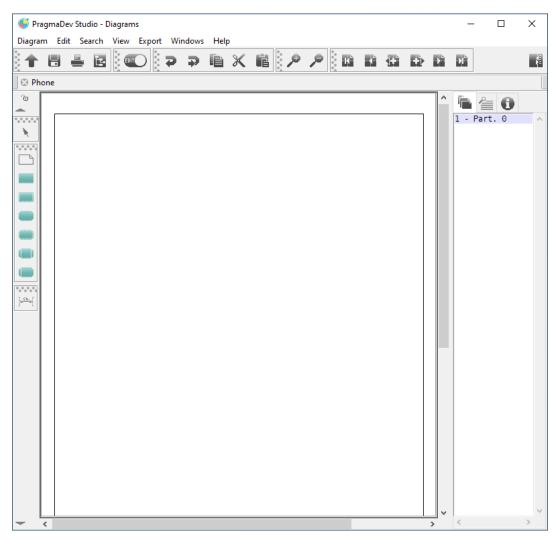


After validating the dialog, the system appears in the project:



"Phone" SDL system in the "Phone" project

Double click on the system name or icon to open the system diagram in the SDL editor:



The SDL editor

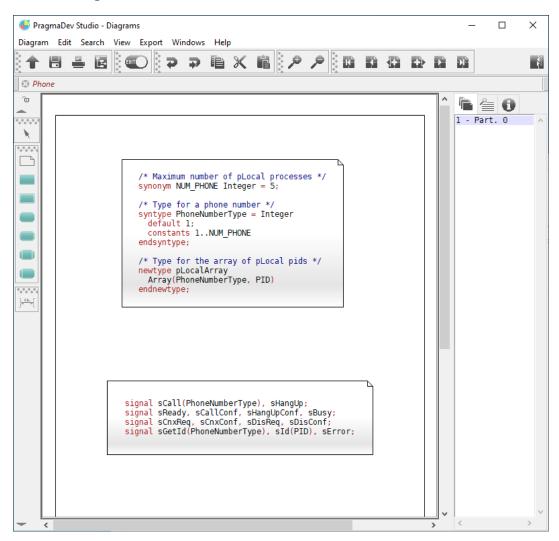
The system will be divided into two main parts:



- The definition of the data types and messages we will use.
- The architecture in terms of processes.

To avoid mixing things, we will use partitions in the diagram. A partition is just a means to separate different kind of contents within a diagram; it is just a group of pages that can contain any symbol allowed in the diagram.

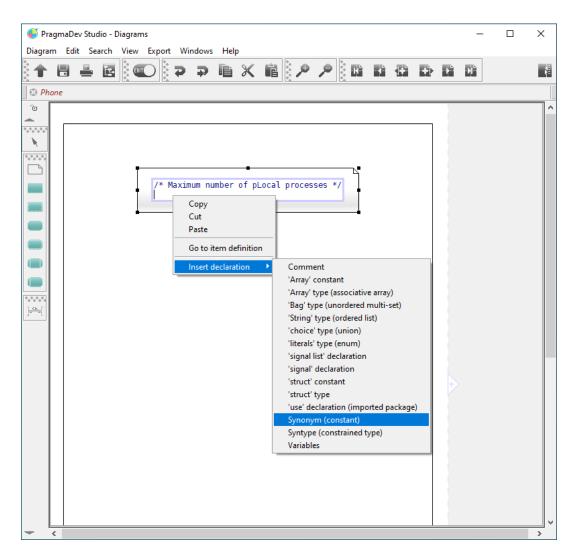
PragmaDev Studio has created the first partition for us, so let's use it to declare the types and messages we'll need:



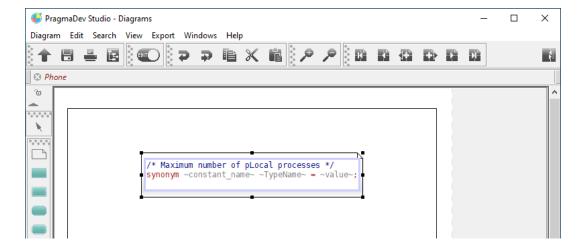
Declarations in the "Phone" system

You actually don't need to type the declarations completely, since PragmaDev Studio provides a way to directly insert skeletons for all kinds of declarations. To insert a skeleton, open the symbol text for modification, then right-click in the text box. The following menu appears:





After selecting the declaration kind, the skeleton is inserted in the symbol text:



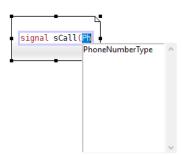
The parts that need to be specified are surrounded by "~" characters and colored in gray. Here, the constant name, the type name and the value have to be specified. Here are the data and types we need:



- The synonym declaration ("Synonym (constant)" in the "Insert declaration" menu) declares a constant for the maximum number of phones;
- The syntype ("Syntype (constrained type)" in the "Insert declaration" menu) declaration declares a special type for the phone. This is basically an integer restricted to be between 1 and the maximum number of phones;
- The newtype declaration declares the type for the array of phone processes ("'Array' type (associative array)" in the "Insert declaration" menu); the index is a phone number, and the value is a PID, which is a basic type in SDL, just as Integer.

The second declaration text box declares the signals that will be used in the system. They are mainly the ones we used in the MSC we created earlier, plus a few ones for error conditions. Three of the signals we declare have parameters: sCall, sGetId and sId. Note the sCall and sGetId signals use the PhoneNumberType type we've declared above.

Declaration skeleton insertion is not provided for signals, but PragmaDev Specifier will offer to auto-complete your code as you type. So for example, when declaraing the sCall signal, if you start to type the signal parameter type, a list will appear under your text cursor listing all known types that start with the text you've already typed:



You can select one of the choices by using the up and down arrow keys, or by clicking on it in the list. Note that entities defined in a symbol are known only when the symbol has been validated, and if its syntax is correct.

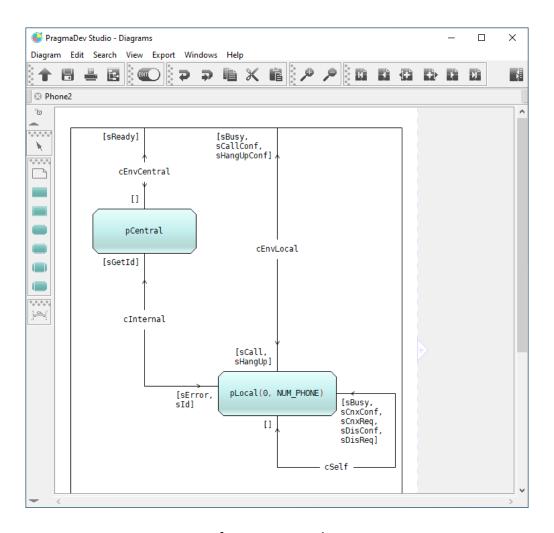
Now let's design the architecture of the system. As we said, we'll use another partition, so let's create it first, using the new partition button in the partition tool-bar:



A new empty partition appears. What you've already done is of course not lost: you can go back to it using the other buttons in the partition tool-bar.

The system being very simple it will not require any block decomposition. The central will be a process as well as the phones. All the phones have the same behavior so they will be several instances of the same process. The phone system is therefore made of two processes. For better legibility their name will be prefixed with a "p" because they are processes:





phone system view

Notes:

- This architecture is not strictly correct in regular SDL, since processes should not appear directly at system level. But PragmaDev Studio allows it, so let's keep things simple.
- To draw the cSelf channel keep the shift key down and click where the channel should break. To change the position of the channel name, click on a segment, right-click on it and select *Set as text segment* in the contextual menu.
- Signals and the NUM_PHONE constant have already been declared, and process names appear in the MSC. So their names will be auto-completed by PragmaDev Studio.

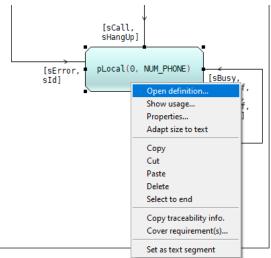
Since pCentral is making the link between the pLocal processes and considering the number of phones can be modified, pCentral will create all instances of pLocal. To represent that, the name pLocal is followed by the initial number of instances and the maximum number of instances we defined in the synonym in the other partition.

Messages to be exchanged between the processes are listed in the channels pecify the incoming and outgoing messages in the diagram double click on the "[]" and type in between the square brackets. The channel going to the outer frame is implicitly connected to the environment. In the above example the channel cEnvLocal connects pLocal to the environment and defines sCall and sHangUp as incoming mes-



sages and sCallConf, sBusy and sHangUpConf as outgoing messages. The channel cEnvCentral connects pCentral to the environment and defines sReady as an outgoing message. The cSelf channel has been created to represent messages exchanged between the different instances of pLocal.

Select pLocal and click on the right mouse button to open the process definition, or simply click on the button that appears when you hover the mouse pointer over it:

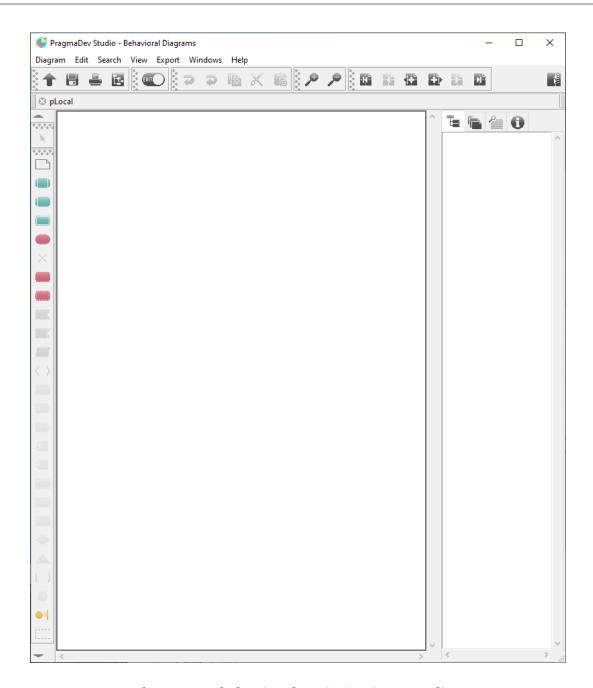


Contextual menu

Since the process is not in the project, it will be asked what type of element must be added. Keep the pre-selected options, *Process* element in *Behavior* and click OK.

A new window opens, showing the process definition. As for the system, the first partition has been automatically created:





The process behavior description in SDL editor

The first thing to design is the start transition. It is what the process will do as soon as it is created. In the case of pLocal process, we do nothing:



That transition means that once the process is started it will go to state Idle. Place a start symbol —, keep it selected and click on the state symbol in the tool bar —. The

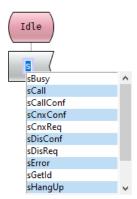


state symbol is automatically inserted and connected after the start symbol. An internal data dictionary is updated on the fly to ease the writing of the process behavior. First create the Idle state definition: click on the State icon and put it in your diagram:



The state name is in edit mode so you can directly type Idle in it; but you may also use auto-completion to list the available choices for the state symbol.

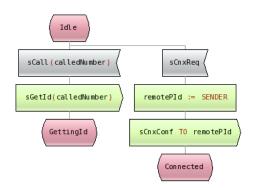
Once the state has been defined, click on the input symbol in the tool bar and the input message symbol will be automatically inserted below the state symbol. When you start typing, a list of all available messages will appear:



Select the sCall message and complete it with the correct parameter. This facility is context sensitive and works for almost everything: SDL keywords, agents, channels, signals, states, types, variables, timers, You can now finish the state description by yourself as explained below.

Considering the requirements described earlier, the pLocal process can either be asked to make a call by the operator or receive a call from another phone. The Idle state can therefore receive two types of messages described below:

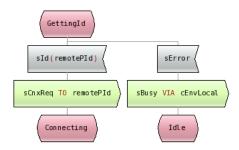




When receiving sCnxReq message, it will reply sCnxConf to the sCnxReq sender. To and sender are SDL keywords in the output symbol. The sender id is stored in the remotePid variable. The process then goes to Connected state.

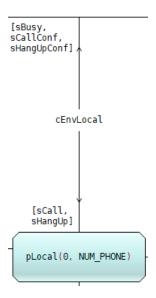
If asked to make a call, the phone number to call needs to be retrieved. To do so, a variable of the correct type is given as parameter of the receiving message. It will be assigned when this message is received. Since pLocal has no idea how to address a phone number it asks the central process the process id of the called pLocal with the sGetId message. The calledNumber variable is re-used as is. No receiver is specified since the receiver process is completely determined by the system architecture. We may however have used TO pCentral to specify it, or even to parent since pLocal was created by pCentral. The process then goes to GettingId state, waiting for the central to answer.

Once the pid of the remote phone is received from the central, it is stored in a local variable and the connection request message sCnxReq is sent. The process then goes into state Connecting. If the pid of the receiver was not found, the sError signal is received. A sBusy message is sent back to inform the user and the process goes back into state Idle:



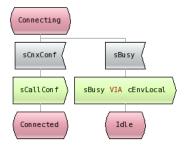
Note the receiver for the sBusy message is specified by using VIA cEnvLocal. It means that the signal will be sent to the process at the other end of the channel cEnvLocal, connected to the process pLocal in the system diagram:





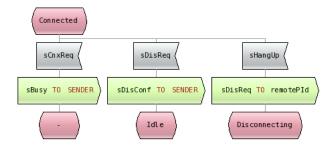
Since this channel is connected to the system's external frame, the signal will go to the environment. Please note specifying a receiver for sBusy is necessary here, since this signal may be sent not only to the environment, but also to the other pLocal processes in the system. If a receiver is not specified, the SDL semantics is to choose randomly a receiver among the available ones, so the signal may have been received by the wrong process.

Once the connection request has been sent, the remote process is either available and replies sCnxConf, or not available and replies sBusy:

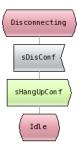


Depending on the answer the resulting state is different.

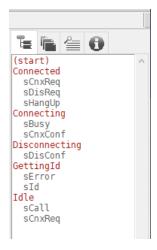
Now that you have understood the basics of the finite state machine you can complete the process behavior:







As the description is done, the browsing window on the right side is updated allowing to quickly jump to a transition: just click on the transition. This is especially useful when the system gets big.



It is now time to declare variables in our process. To do so, the text symbol in the process behavior diagram is used. The declarations are introduced via the keyword DCL, followed by a list of couples <variable name> <variable type>, with an optional default value:



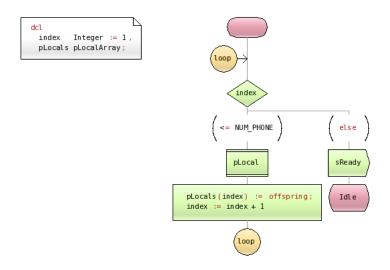
Just as for types, a skeleton for the declaration can be inserted via the contextual menu (entry 'Variables' in the 'Insert declaration' submenu). Note the type of the variable used in the input and output symbols for sCall and sGetId are not strictly the ones appearing in the definition: the signal declares a PhoneNumberType, but we use a regular Integer. This is no problem as long as the Integer satisfies the conditions set on the PhoneNumberType type.

Let's have a look at process pCentral now. It must do the following things:

- At startup, it creates all instances of pLocal and gives them a new phone number.
- When asked for a phone number, it sends back the pid for the corresponding process.



Go to the system diagram Phone, and open pCentral (via the contextual menu or the button). Since the process is not in the project, it will ask if it should be added. Answer Yes and a pre-filled Add child element window with the process name appears. Click OK and the process definition window appears. Let's first write the needed declarations and the initial transition:

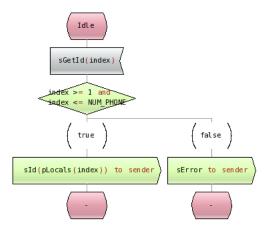


The variables include an index which will be used as the phone number for created pLocal's, and an array mapping the phone number to the pid.

The initial transition creates all instances of pLocal within a loop testing index <= NUM_PHONE. Each time the loop is executed the pLocal process is created and its process id (offsrping keyword for the parent process) is stored in the pLocals array, using the phone number as index.

After the pLocal processes creation, the sReady signal is sent to the environment to indicate initialization is finished and the process goes to state Idle.

Note we have voluntarily introduced an error by typing "; " instead of ", " at the end of the first line in the lowest block of code to later show how to analyze the errors.





The only request that can be received by pCentral process is sGetId. The phone number to reach is the parameter passed to the signal, which we will receive in the index variable. The process id of the phone is extracted from the array and sent back directly to the sender of the sGetId message (SDL keyword sender). If the phone number is out of range, an error message is sent back to the sender.



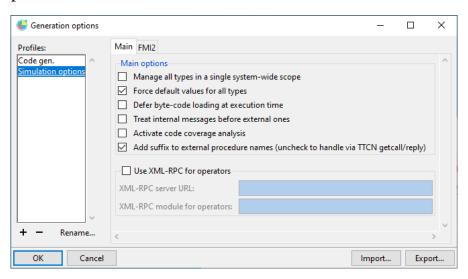
3.4 Simulating the system

Now that the system has been designed, we'll debug it using PragmaDev Studio's SDL simulator. The simulation process is divided into two main phases:

- First, the code for all transitions in all system's processes is transformed into an internal representation called SDL byte-code. This language is used only internally and has no direct external representation.
- The generated byte-code is then executed based on a scheduling managed by PragmaDev Studio model debugger. The simulation conforms to the SDL semantics: all transitions are executed in no time and cannot be interrupted.

3.4.1 Simulation options

The Simulation options and the code generation options are edited via the *Generation/* Options... menu. By default a valid simulation profile is listed as well as an empty code generation profile:



As the simulation profile is the only valid debug profile, it will be used by PragmaDev Studio by default.

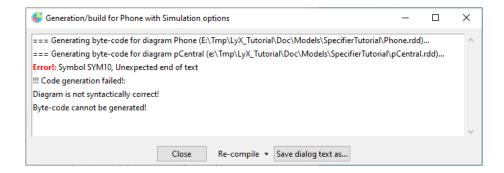
3.4.2 Byte-code generation

Select the Phone system in the project manager and click on the *Execute* quick button in the tool bar:

A log window opens and displays the actions performed by the byte-code generator. Before actually generating anything, PragmaDev Studio performs a global syntax and semantics check on the written code. So any basic error such as typing mistakes or misspelling in variable names will be reported during this phase.

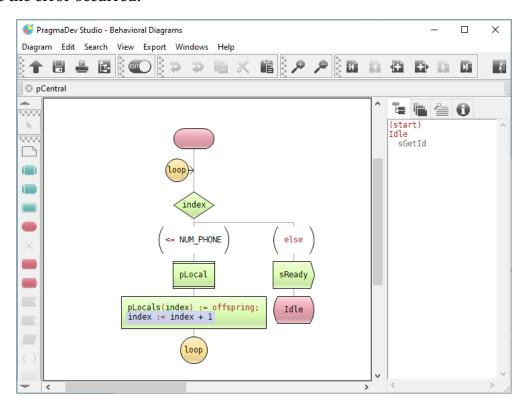
Since we introduced an error in process pCentral, this is what appears in the byte-code generator log window:





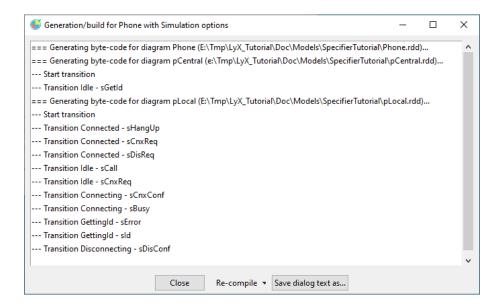
The byte-code generation started at system level, then went down in pCentral. During the generation for pCentral's start transition, the inversion between ";" and "," was encountered. So the generation stopped and this error message was displayed.

Double clicking on the error automatically opens the SDL editor and selects the symbol where the error occurred:



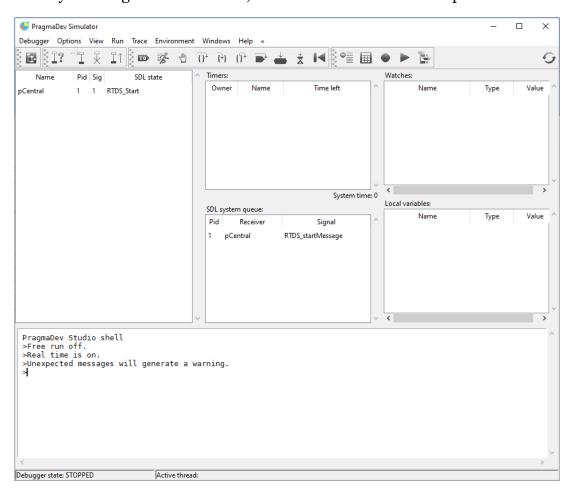
Once the error have been corrected the log window should look like this:





3.4.3 The SDL simulator

Once the byte-code generation is over, the SDL simulator window opens automatically:



The SDL simulator window



The simulator window shows a global state of the running system in terms of:

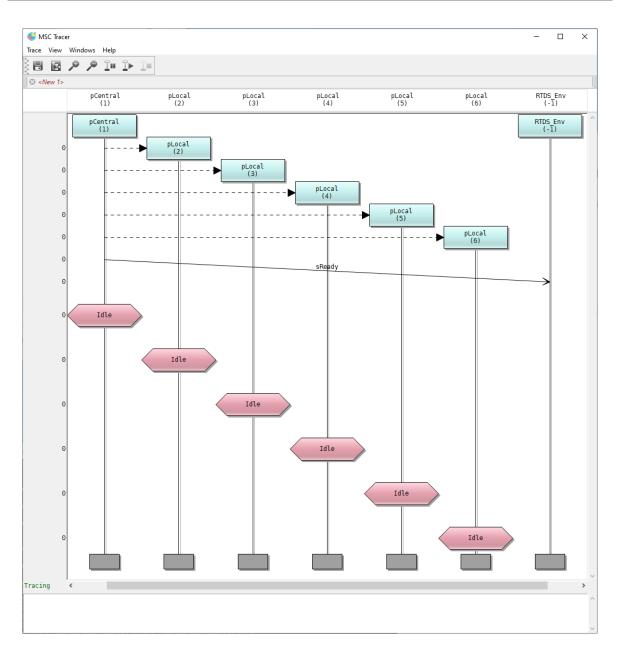
- · Running processes
- · Sent messages
- Started timers
- · Local variables when in the context of a running process
- Watched variables, allowing to see the value of any variable at any time

The lower part of the window is a shell where actions taking place in the system will be reported.

Let's first run a MSC trace so that we can see graphically what is happening in the system. Click on the *Start MSC trace* quick button: A *MSC Tracer* window appears.

Now let's actually start the system by clicking on the *Run the system* quick button: Let the system run until all pLocal processes are created by pCentral and their start transition executed:





Note you can detach the execution buttons bar by dragging it away from its header (the zone looking like this: - if you don't see it, go to the preferences in the "Studio" menu of the project manager, and check the option "Detachable toolbars" in the "General" tab):



Detached execution buttons toolbar

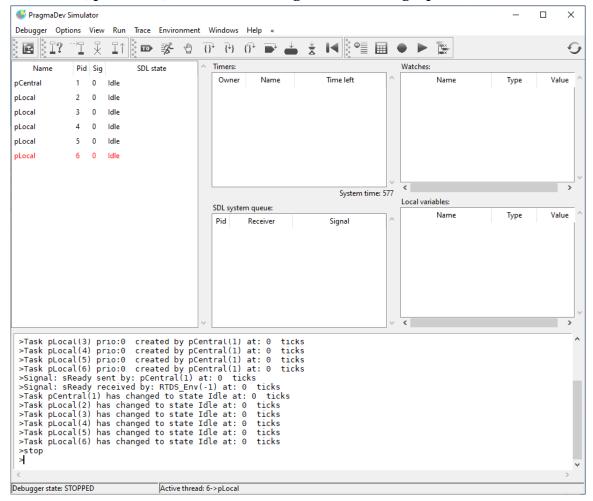
The environment is represented by the pseudo-process RTDS_Env. This is not really a process as it does not appear in the list of running processes in the simulator window and has no code associated. It is only used to trace messages sent from and received by the environment.



Process pCentral dynamically creates 5 instances of pLocal, sends the sReady message to the environment and goes to state Idle. Each pLocal instance then go to state Idle. On the left is the value of the system time. According to SDL semantics, all start transitions executed in no time, so the system time is still o after all processes have started.

Click on the *Stop* button to break execution:

The SDL simulator window shows the list of all running processes, displaying for each one its name, process id, number of messages in its message queue and SDL state:



SDL simulator window

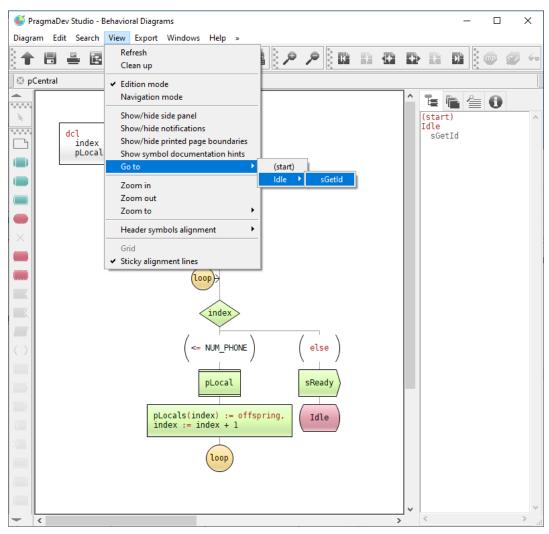
Now let's put a breakpoint in process pCentral:

- Open pCentral from the project manager, or by double-clicking its name in the instance list in the simulator window.
- Go to the transition for signal sGetId in state Idle using the state/message browser:



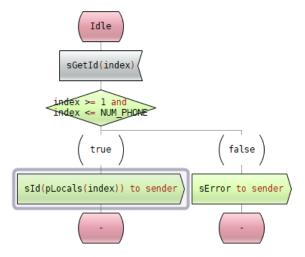
or the *View* menu:





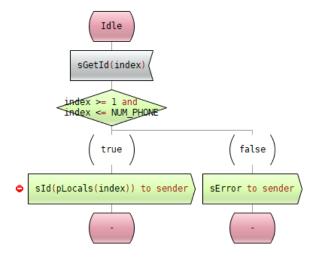
The state/ message browser and the *View/ Go to* menu allow to quickly navigate among the transitions defined in the process. Selecting the transition will automatically open the partition where the transition is and scroll to the corresponding signal input symbol.

• Click on the signal output symbol just after the decision's true branch:



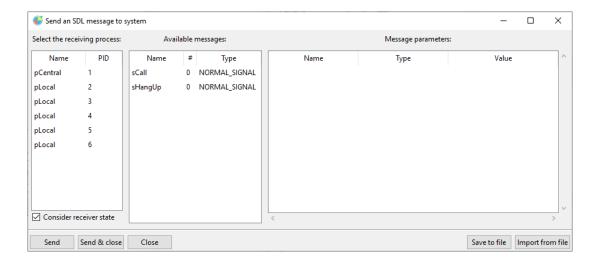


• Click on quick-button or go to *Debug / Set breakpoint* menu in the *SDL* editor. A breakpoint symbol is displayed on the side of the selected symbol:



We will now simulate an incoming message from a user:

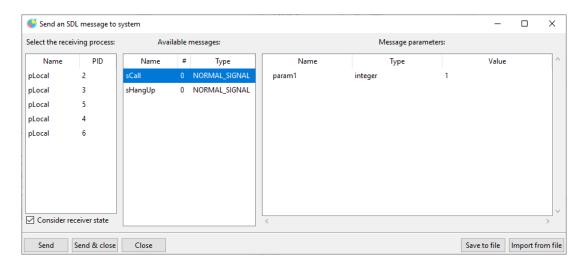
- Go to the *SDL Simulator* and click on "Send an SDL message to the running system" quick-button
- The Send an SDL message window shows up:



Send an SDL message window

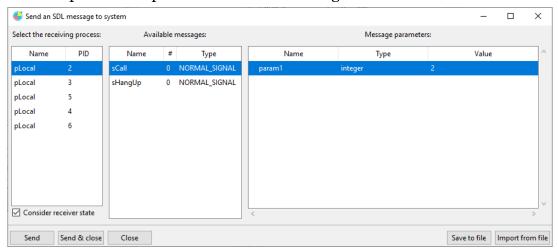
On the left are listed all possible receiving processes, in the middle all possible messages, i.e. all messages used in the SDL system, and on the right the value of the parameters associated with the selected message. Clicking on either the message or the receiver will restrict the other list to show only the consistent choices. Here, we want to send a sCall signal, so let's select this signal in the list:





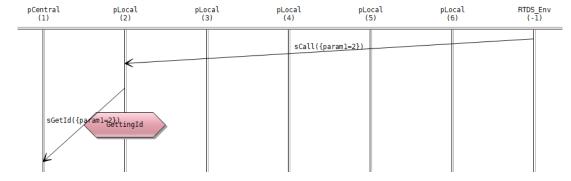
Since process pCentral cannot receive signal sCall, it disappears from the list of available receivers.

• Now let's select the signal receiver and input the called phone number, which should be passed as a parameter to the sCall signal:



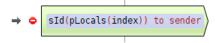
The signal parameters are described in the right part of the signal send window. Double click on the parameter to edit its value and hit *<Enter>*.

- Click the Send & close button.
- Resume system execution by clicking the *Run* button in SDL simulator window.
- The following actions appear in the MSC trace:

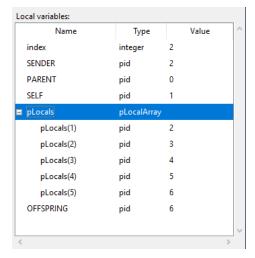




• When the breakpoint is hit: the SDL editor then pops up and displays the symbol where the execution has stopped:

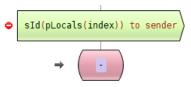


• Since we are in the context of a running process, local variables are automatically displayed in the SDL simulator window. All complex variables such as structs or arrays can be expanded to show their contents. Here are the local variables with the pLocals array expanded:

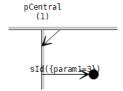


You can see the value for index is 2, so the value sent with the sId message will be the pid stored at index 2 in pLocals, i.e. 3.

• You can also execute instructions line by line in the symbols by using the *Flat* step quick-button: {}



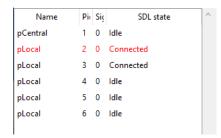
(NB: you may have to click on the button twice to go to the next state) The signal send has been done, as shown in the MSC trace:



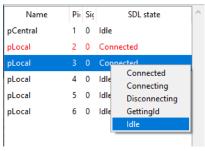
- Let's now finish the system execution by pressing the *Run* button once more.
- When the signal sCallConf has been received by RTDS_Env in the MSC trace, stop system execution with the button $\ ^{\textcircled{1}}$

The SDL states for all running processes are updated in the simulator window:



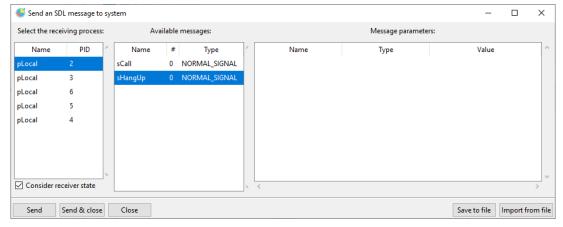


• The SDL state of a process can be dynamically changed using the contextual menu in the process list:



Some caution is required with this feature, since it may have unexpected results on the system behavior...

• We will now disconnect the two connected pLocal processes by sending another signal. So press once more:



This will send a sHangUp signal to the first pLocal (the receiver for our sCall message) with no parameters.

- Send the message with the *Send & close* button.
- We saw that stepping could be done at code line level. There are other step levels including:
 - Step at SDL event level with button
 This button will step one SDL event at a time. Click on it while looking at the MSC trace; you'll see that each time a SDL event happens (signal send, signal receive, process creation, timer start, and so on...), the system execution stops just after the event.
 - Step at transition level with button —

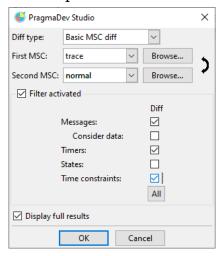


This button will execute a whole transition and stop just after its end (usually the next state symbol). Click on it while looking at the MSC trace; you'll see the active process execute all actions in current transition up to the state change, and the system execution stops.

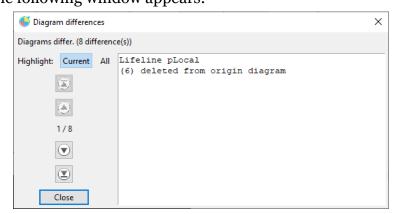
3.4.4 Verifying the behavior

We will now check if the behavior is the one we expected in the first place. To do so we will use the MSC diff feature.

- Make sure the execution is over by clicking button 3 a last time. Then go to the MSC trace window, save the trace and close it.
- Close the simulator window.
- In the project manager, open the trace diagram.
- Go to the *Diagram / Compare with other diagram...* menu to get the MSC Diff configuration window and set it up as described below:

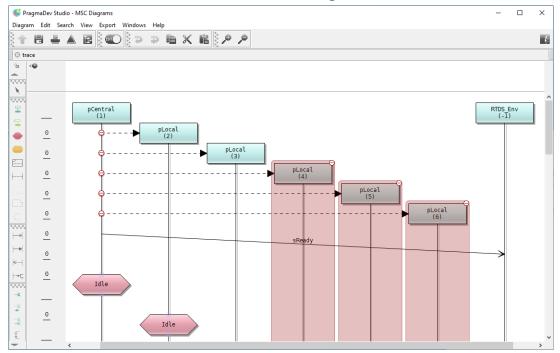


The first MSC is the trace and the second is the normal scenario we described in the first place. Since the normal MSC was not supposed to be thoroughly detailed we will only show and compare messages without considering their parameters. Click *OK*; the following window appears:





It allows navigation through the differences between the MSCs. By selecting All, then all the differences will be shown in the diagram:



The only differences between the MSCs are the dynamic task creation of the pLocal instances. After that the exchange of messages are the same between the dynamic trace and the specification. The SDL system therefore conforms to the normal MSC specification.

This is the end of this very simple SDL simulation session. There are many areas that have not been covered, such as timers, procedures, external operators, system queue manipulations, watched variables, and so on... You may discover all these features yourself using the examples delivered in PragmaDev Studio distribution or by designing your own system.

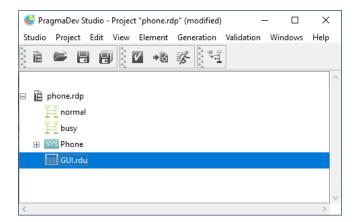


3.5 Prototyping GUI

PragmaDev Studio has a built in support to design simple prototyping interface to ease testing. We will build a very simple one for our phone system to demonstrate its capabilities.

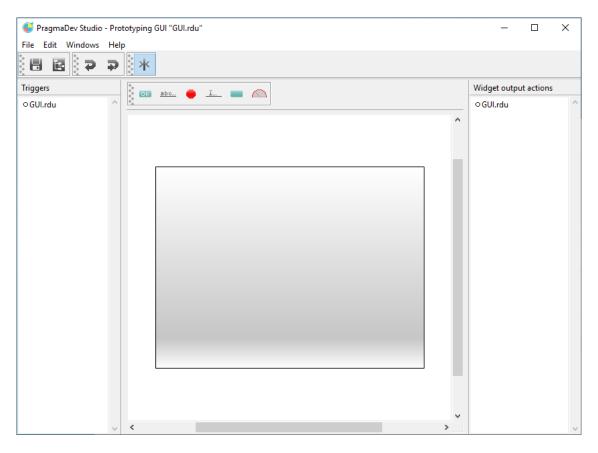
3.5.1 GUI editor

Add a Prototyping GUI node in the project (category Testing / Validation in the Add child element dialog) and open it:

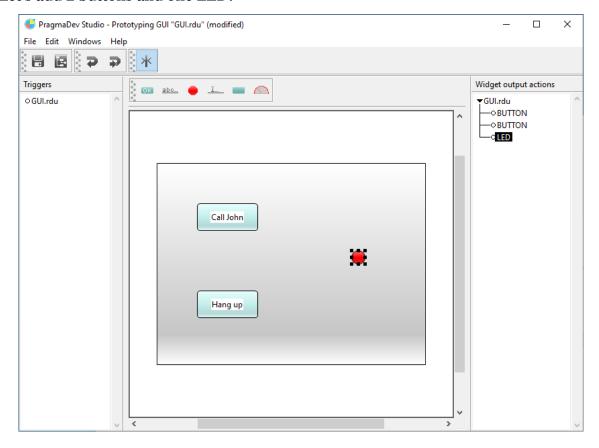


The left panel contains the incoming triggers for the GUI, the central panel the GUI itself, and the right panel the outgoing message from the GUI:



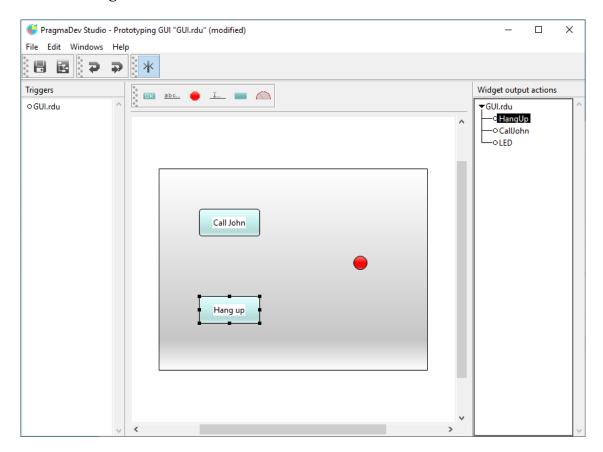


Let's add 2 buttons and one LED:





Change their display value in the central panel and their widget name in the right panel in order to recognize them:

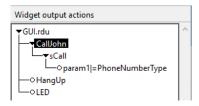


Let's say that when the user clicks on the "Call John" button, the GUI sends an sCall message with parameter set to "2". Select the Call John widget on the right panel and right click:

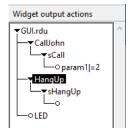


All the available messages in the system are then listed. Select sCall and expand the created sub-tree. The parameters are listed with their corresponding type:

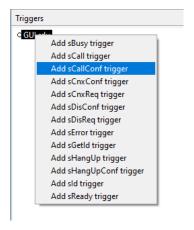




Let's say the parameter value is '2' and let's send sHangUp without any parameter when clicking on Hangup:



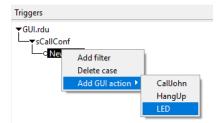
On the left panel now, we will add a new trigger. A trigger performs some action on the widgets whenever a message is sent out of the system. Select the top of the tree and right click to get a list of all the possible triggers:



Let's add the sCallConf trigger. When a trigger is received by the GUI, a case with a set of filters is verified. Let's add a new case:

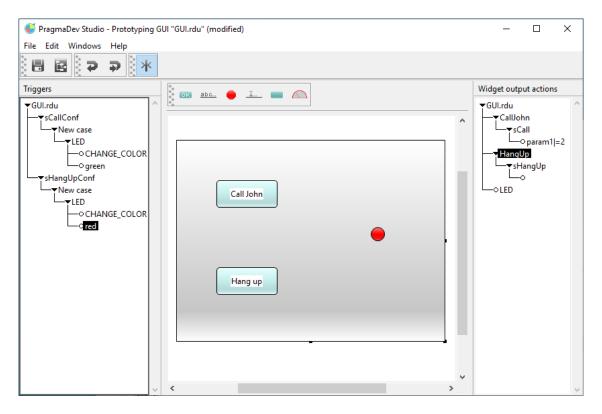


In our case we won't put any filter, we will just change the color of the LED:





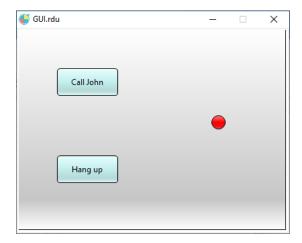
The default action is DISPLAY; you'll have to right click on it to change it to CHANGE_-COLOR. The node in the tree under the action specifies the new color for the widget. It is possible to directly name the basic colors, otherwise the RGB hexa code can be used (e.g #FF8000 is this color). Let's put the LED back to red when we receive a HangUp confirmation and we're done:



3.5.2 Simulation

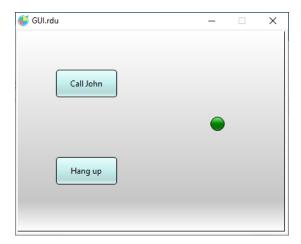
Let's start the Simulator again and click on the Start prototyping GUI quick button:

The GUI will start and connect automatically to the system:





Start an MSC trace and run the system. Click on the "Call John" button, that should send the sCall message with parameter value set to 2, the sCallConf should be received by the GUI, and the LED should be set to green:



In practice, this is not a good example because there are a lot of different pLocal processes that could receive the messages sent by the GUI so the receiver is randomly selected.

For a more advanced GUI, please have a look at the AccessControl system in the Specifier example directory.

3.6 Conclusion

During this tutorial we have been through:

- SDL,
- · Project manager,
- SDL architecture & behavioral editors,
- MSC editor,
- SDL simulation including three stepping modes:
 - SDL code line,
 - SDL event.
 - transition,
- Conformance checking,
- Prototyping GUI.

As a result, you saw that SDL is perfectly suited to describe high-level specifications for real time systems. Its complete description covering architecture, behavior and abstract data types allows you to fully describe your system independently from the target implementation such as the processor, the RTOS or even the implementation language. The following chapter will explore some PragmaDev Studio specific features such as

testing and code generation.

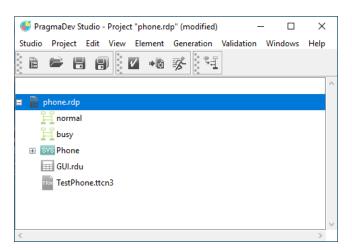


4 PragmaDev Studio

This chapter follows the PragmaDev Specifier Tutorial part. Please follow the previous chapter before continuing.

4.1 Testing

PragmaDev Studio supports TTCN-3 standard testing language for edition and simulation. We will build up a small test case and run it on the phone system we have just designed. Let's add a TTCN-3 component to the project (category *Testing / Validation* in the *Add child element* dialog) and name it TestPhone:



4.1.1 Test case

The text editor recognizes the TTCN-3 syntax so all the keyword will be highlighted. Here is the test suite we will explain in the following paragraphs:



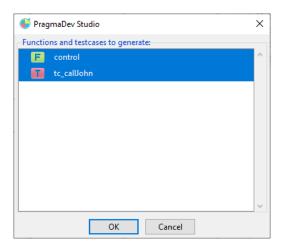
```
🌓 PragmaDev Studio - Text files
File Edit Search View Preferences Windows Help «
 電 X 幅

☑ TestPhone.ttcn3

        // Data types
           type integer PhoneNumberType (1..5)
            // The messages
           type record sCall {
             PhoneNumberType param1
// The ports
           type port cEnvLocal_type message {
             out sCall:
             out sHangUp;
             in sBusy;
in sCallConf;
              in sHangUpConf
           type port cEnvCentral_type message {
             in sReady
            // The SUT - System Under Test
           type component Phone {
             port cEnvLocal_type cEnvLocal;
port cEnvCentral_type cEnvCentral;
           // Templates definitions
           template sReady SystemIsReady
template sCallConf CallConf
                                             := ?;
           template sBusy Busy
template sCall John
                                             := ?;
                                             := { param1 := 2 };
            // the test cases
           testcase tc_callJohn() runs on Phone
              cEnvCentral.receive(SystemIsReady);
              cEnvLocal.send(John);
              alt
                []cEnvLocal.receive(CallConf)
                  setverdict(pass);
                []cEnvLocal.receive(Busy)
                  setverdict(fail);
            // The control part
           control{
              var verdicttype verdict1;
              verdict1 := execute(tc_callJohn());
   E:\Tmp\LyX_Tutorial\Doc\Models\SpecifierTutorial\TestPhone.ttcn3 line 1
                                                                    0 selected
                                                                              22 bytes
```

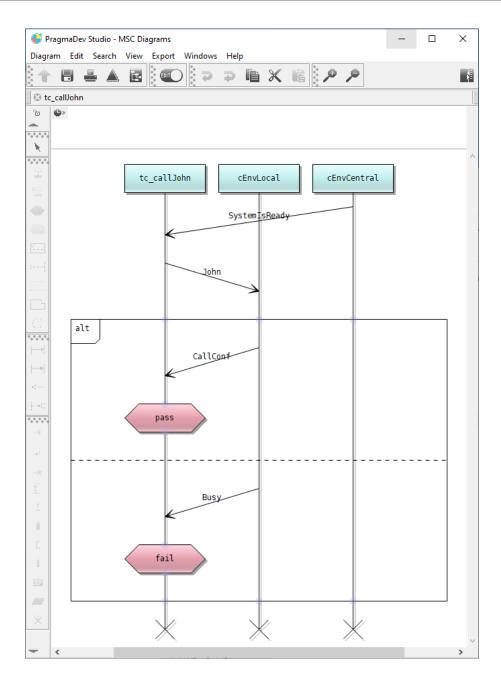
To see a MSC representation of the TTCN-3 tescase behaviour, click on the View graphical representation button:





You can select the functions and test cases you wish to visualise. In our simple case we will generate everything:





This MSC representation is not editable.

Since TTCN aims at testing complex systems, it is strongly structured. We first need to define the data types we will be using in our test case, define the interfaces with the system, and the value templates that will be exchanged.

4.1.1.1 Declarations

The messages exchanged between the system and the environment are the ones listed in the channels connect to the frame of the system. Most of the message exchanged with the system have no parameters except sCall. sCall takes an integer sub-type as a parameter we will re-define here:



```
// Data types
type integer PhoneNumberType (1..5)
```

There is no message or signal specific type in TTCN: if the message has parameters it is defined as a record, and if it has no parameters, it is defined as an enumerated with a single possible value. Just as in symbols, skeletons for all kinds of declarations can be inserted in the TTCN file via the contextual menu, submenu 'Insert declaration', then the declaration kind:

- "'enumerated' type (enum)" for enumerated types;
- "'record' type (struct)" for records.

Here are the TTCN declarations to create:

```
// The messages
type record sCall {
   PhoneNumberType param1
   }
type enumerated sHangUp { e_sHangUp }
type enumerated sBusy { e_sBusy }
type enumerated sCallConf { e_sCallConf }
type enumerated sHangUpConf { e_sHangUpConf }
type enumerated sReady { e_sReady }
```

4.1.1.2 Ports

TTCN-3 can test asynchronous systems, synchronous systems, or a combination of both. In our tutorial example only asynchronous messages are exchanged with the system. We will define a port for each channel in the system representing the 2 interfaces:

```
// The ports
type port cEnvLocal_type message {
  out sCall;
  out sHangUp;
  in sBusy;
  in sCallConf;
  in sHangUpConf
  }

type port cEnvCentral_type message {
  in sReady
  }
```

Just as for other declarations, a skeleton for a port type can be inserted via the contextual menu, then "Insert declaration", then "Port type for asynchronous messages".

We will now define the component we will be testing, that is the system itself. The name of the component must be the name of the SDL system.



```
// The SUT - System Under Test
type component Phone {
  port cEnvLocal_type cEnvLocal;
  port cEnvCentral_type cEnvCentral;
};
```

A skeleton for a component type definition can be inserted via the contextual menu, then "Insert declaration", then "Component type".

4.1.1.3 Templates

When exchanging messages with the system, the values of the parameters of the messages must be pre-defined. These values are called templates. Templates are used to both:

- define the values of the outgoing messages parameters,
- to verify the values of the received messages parameters are correct.

In our phone example, the messages coming from the system do not have any parameter, only the sCall message has one parameter. Still we need to define templates for all the message we will exchange with the system.

```
// Templates definitions
template sReady SystemIsReady := ?;
template sCallConf CallConf := ?;
template sBusy Busy := ?;
template sCall John := { param1 := 2 };
```

The John template will set the parameter of sCall to '2'.

4.1.1.4 Core test case

The core test case is the execution part, the scenario itself. To make it simple, we will first wait until the system sends the ready message on the cEnvCentral port, then we will call John and wait for the answer. An alternative is created: the call is confirmed and we will consider the test pass, or John is busy and we will consider the test fail:

```
// the test cases
  testcase tc_callJohn() runs on Phone
  {
    cEnvCentral.receive(SystemIsReady);
    cEnvLocal.send(John);
    alt
      {
       []cEnvLocal.receive(CallConf)
       {
          setverdict(pass);
    }
}
```



```
}
[]cEnvLocal.receive(Busy)
{
   setverdict(fail);
   }
}
```

A skeleton for a testcase definition can be inserted via the contextual menu, then "Insert declaration", then "Testcase". Note that the skeleton will also include a "system" clause that we are not using here, so it can just be deleted.

For the testcase body, it is also possible to insert a skeleton for the 'alt' block using the contextual menu, then "Insert statement", then "'alt' statement".

4.1.1.5 Control part

The control part is what will be executed, this is where you combine which test case you would like to run on the system. Please note there might be a different verdict for each test case. This won't stop the execution of the control part. In our tiny example we will just run the unique control part we wrote:

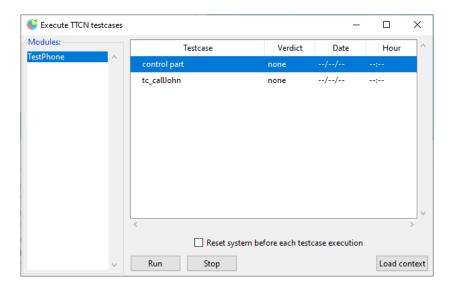
```
// The control part
control{
  var verdicttype verdict1;
  verdict1 := execute(tc_callJohn());
}
```

We're done with our test case, let's now run the test on the system and see what it does.

4.1.2 Simulation against the SDL system

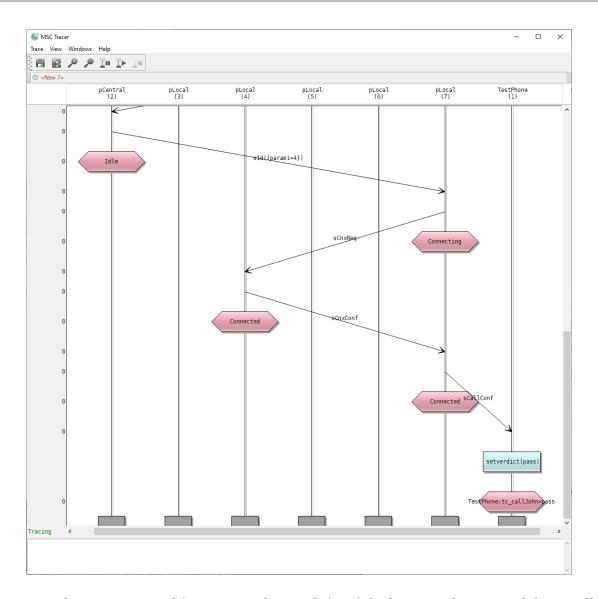
Select the test suite in the project manager and click on the *Execute* button. In addition to the PragmaDev Simulator, the following window will open:





Please note it is possible to set breakpoints in the test case as well as in the SDL system. Start an MSC trace, select the control part, and Run. The scenario will execute by itself and the verdict is displayed in the shell and in the MSC trace:





Because there are several instances of pLocal, it might happen that one of them calls itself during the test case, causing it to fail. In that case, run the scenario again for the test to pass.

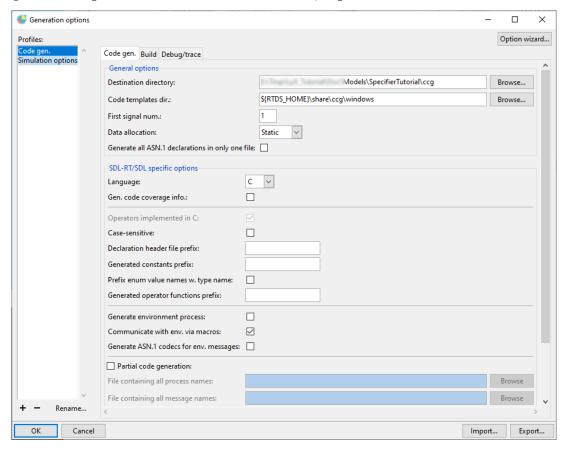


4.2 Code generation

4.2.1 Code generation options

It is possible to generate C code out of the SDL system in order to implement it on a real target. For this chapter, we will use our host computer as a target, and for that we will need a compatible debugger. MinGW is automatically installed on Windows and a compatible gdb version for Linux is available in the distribution. Please refer to the installation manual for further information.

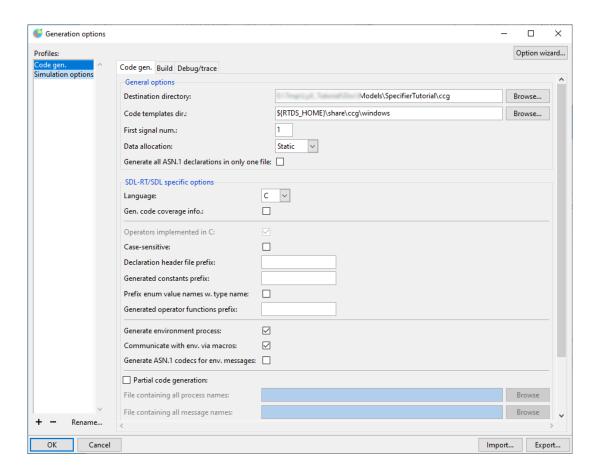
The generation profiles are listed in Generation/ Options...



The directory where the C files will be generated is automatically set to the ccg subdirectory under the project directory. Now we'll use the *Option wizard...* to quickly create a valid profile such as described below:

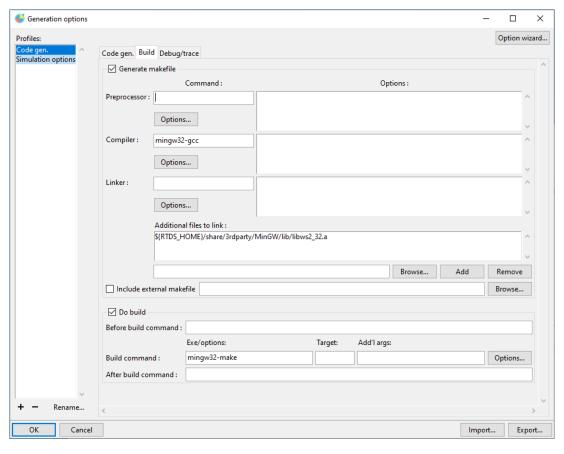


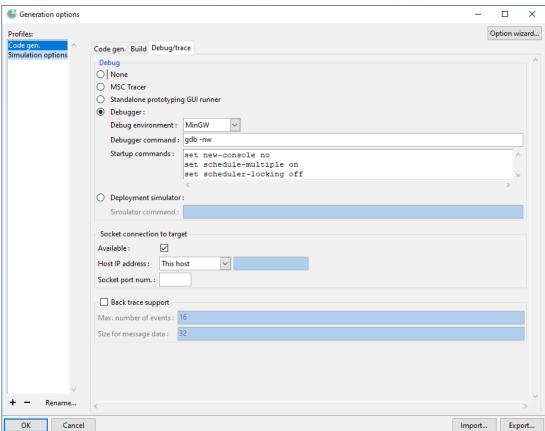




Make sure the "Generate environment process" box is checked.









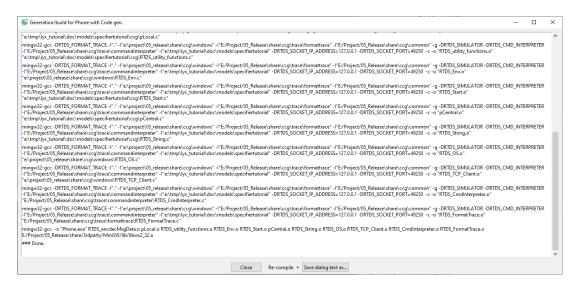
4.2.2 Graphical debugging

Once the SDL debug profile is properly defined select the SDL system in the *Project* manager and click on the *Execute* quick button in the tool bar:

Since several execution profiles are defined, a window pops up asking for the profile you want to use:

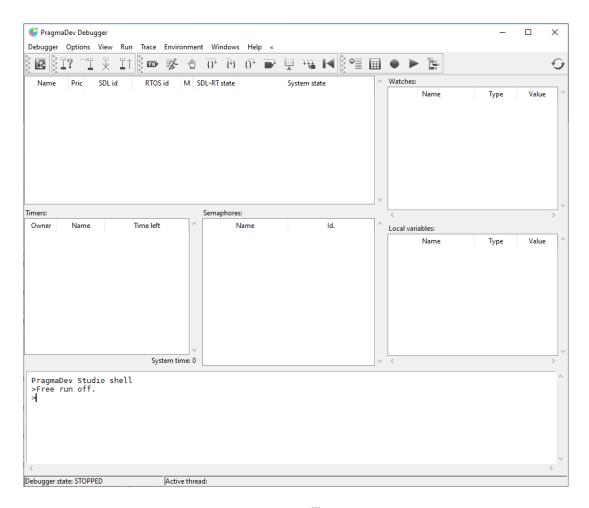


Select *C code generation* and click *Ok*. The code will be generated, compiled, and the debugger will be started automatically:



The debugger interface looks pretty much like the simulator one:

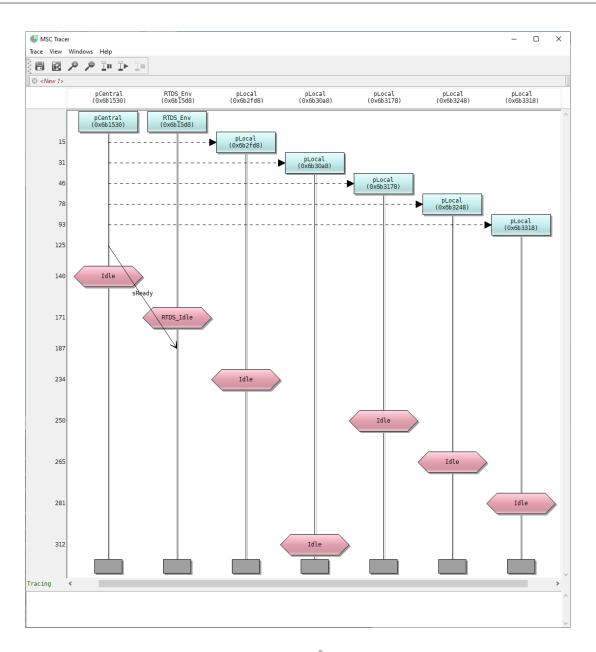




Click on the *Start MSC trace* quick button:

An *MSC Tracer* window appears. Let's start the system; click on 'run' quick button: The MSC Trace will look like the one below:

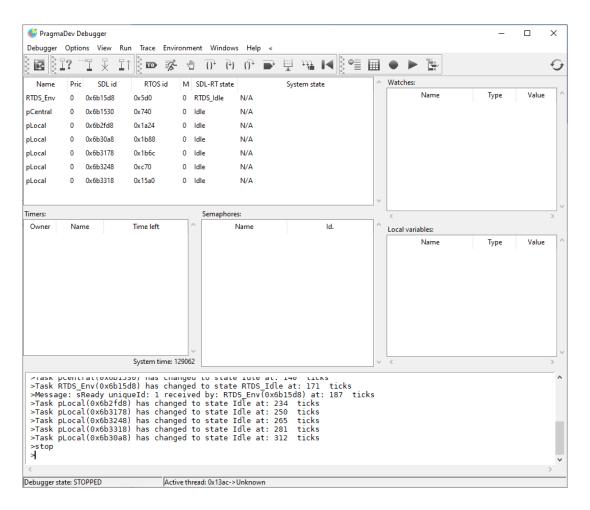




Click on the Stop button to break execution: \Box

The SDL debugger window shows the list of processes with their names, priority, process id, queue id, number of messages in their respective message queues, SDL internal state as we defined in the diagrams, and the RTOS internal system state if available.





As with the SDL Simulator, it is possible to set breakpoints, view the value of variables, send messages... Would you like to know more about graphical debugging of C code, we strongly suggest to go through the PragmaDev Developer tutorial as the debugging features are the same.



4.3 Validation

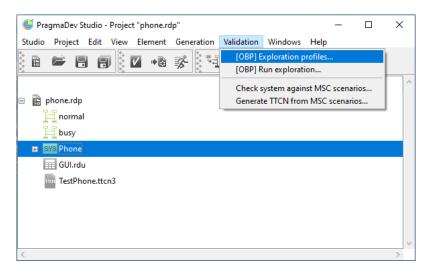
Since SDL is formal, executable and non-ambiguous, it allows for powerful validation techniques that can theoretically prove that the system never causes any problem and even does what it's supposed to do.

The most common verification technique is exhaustive exploration, which will execute all possible paths in the system to look for errors, and can at the same time verify properties to check the semantics of the running system. But the fact that SDL systems are usually infinite loops accepting events from their environment often causes this kind of validation to be impossible, since there is always one more event that can be sent to the running system.

To solve this issue, PragmaDev Studio introduces a way to define limitations on the exploration, allowing to consider only what's relevant in the system and to avoid exploring branches that are not interesting.

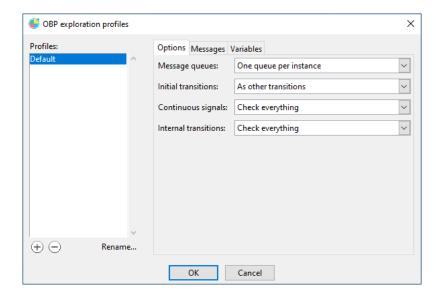
SDL validation uses an external tool developed by ENSTA Bretagne called Object Based Porver, or OBP. OBP actually collaborates with PragmaDev Studio for the exploration of models: it defines what transitions will execute in the SDL system, but the actual transition execution is performed by Studio. This allows to have an execution semantics that is exactly the one used in the tool. Each time a transition is executed, the whole state of the system including all the running instances with their state and their variable values are sent over to OBP, which keeps track of everything it has already explored.

What is sent to OBP from Studio is controlled via an exploration profile. A project can contain several of these. They can be defined by selecting the "[OBP] Exploration profiles..." in the "Validation menu" of the project manager:



This opens the following window, showing a default profile with all options to their default value:

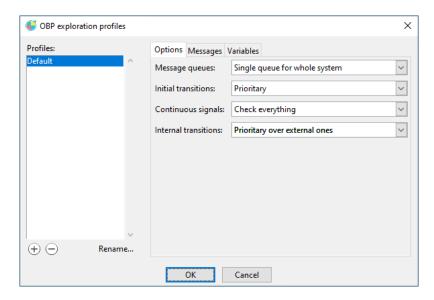




The options in the profile are divided in 3 categories, with one tab in the dialog for each one of them:

- "Options" are the exploration options. They allow to control how message queues are handled and the priorities for special kind of transitions;
- "Messages" allow to define restrictions on messages coming from the environment, in terms of number of messages and values for their parameters;
- "Variables" allow to define restrictions on the variables appearing in the processes, especially if they are relevant in the system state sent to OBP or not.

Let's define an exploration profile for our system. First, we will limit the exploration options to how the execution works in the SDL simulator:

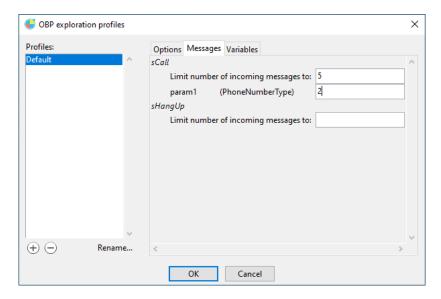


The simulator uses a single system queue for all messages so that's what we'll be using here. We also asked for the initial transitions for all processes to have priority over all other ones, and to execute all internal transitions before considering any messsage coming from the environment. These options shouldn't have any significant impact on



how the system is executed, and they will limit significantly the number of explored states.

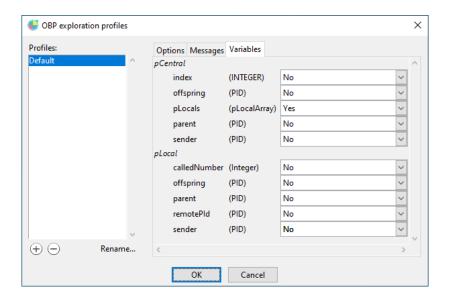
Second, let's define some constraints on the incoming messages:



Here, we limit the number of "sCall" messages sent from the environment to the system to 5. Considering that there are 5 instances of pLocal, this looks like a good value for testing. Also, since all instances of pLocal play the same role in the system, testing all possible values for the called number is not very interesting, so we'll be using only the value 2.

Note that limiting the number of sHangUp messages is not needed: during exploration, a message is sent from the environment to the system only if the instance that will receive it is actually in a state where it will treat the message. Since this messsage is ignored by pLocal instances that are not connected to another instance, there's no point in limiting it.

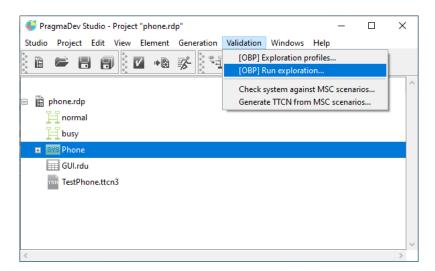
Last, we'll define which variables will appear in the system state sent to OBP:



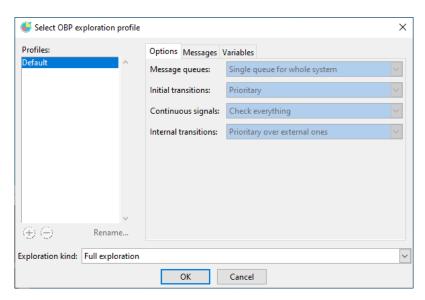


The built-in variables "offspring", "parent" and "sender" are either not used, or their usage is limited to the current transition in both processes, so they do not need to appear in the system state, as they have no impact on how transitions will be executed. In pCentral, the variable "index" also has no impact on transition execution: it is only used as a loop variable in the start transition, and locally in the Idle / sGetId transition: once the transition is over, the value of "index" is not significant. So all these variables are excluded from the system state.

Validate the exploration profile with "OK", then let's select the system in the project manager and run an exploration:

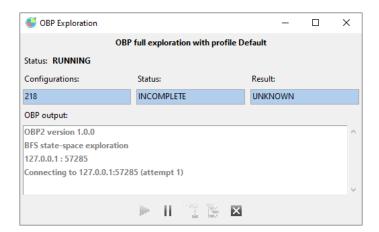


A first dialog appears, allowing to select the validation profile and the kind of exploration to run:

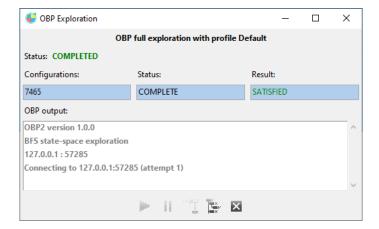


Let's run a full exploration first. The OBP progress dialog appears and the exploration starts:



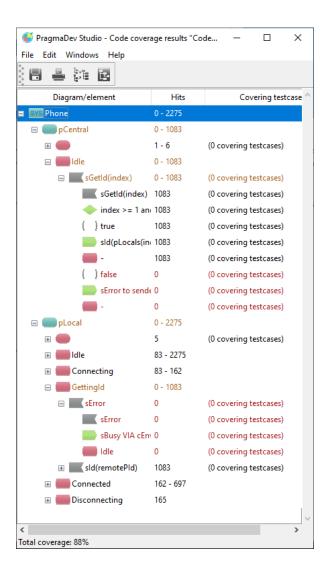


There can be several thousands of states to explore, so give it a little time. Once the exploration is over, the progress dialog will show:



This means all reachable paths in the system with the exploration profile have been explored. We can now ask if there are parts of our system that have never been executed by asking for the code coverage via the button ::

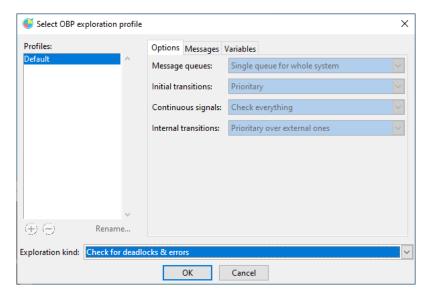




The symbols that were never executed are shown in red with a minimum count of o. Here, we can see that the case where the phone number is incorrect in pCentral is never executed, and looking at how the system is defined, it will indeed never be: the parameter to the message "sGetId" is a PhoneNumberType, which is constrained to be between 1 and NUM_PHONE, so the decision will always select its "true" branch. So the "false" branch is never selected, the message sError never sent, and therefore never received in pLocal either.

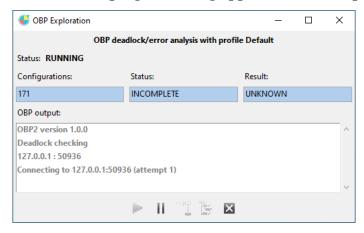
Let's close everything and run another kind of exploration with the same profile:



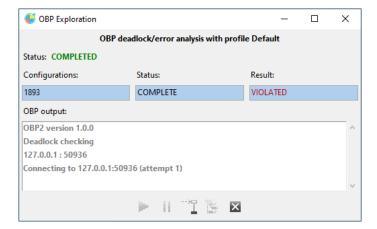


In this mode, OBP will try to find deadlocks in the system, i.e states where instances are still alive, but nothing can happen because they're all waiting for a message that cannot be sent by any other instance. It will also detect errors in the system, for example, if an invalid value is assigned to a variable considering the constraints on its type, or too many instances of a process are dynamically created, and so on...

Once the dialog is validated, the progress dialog appears and the exploration starts:

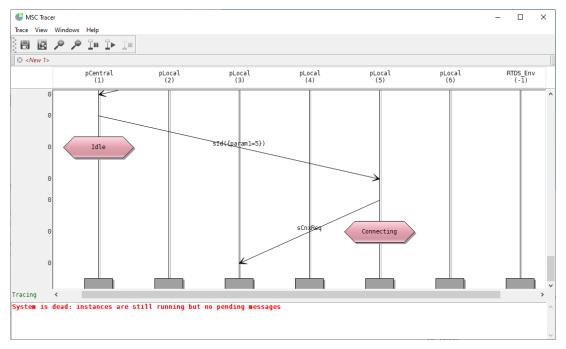


At the end of the exploration, the dialog will show:

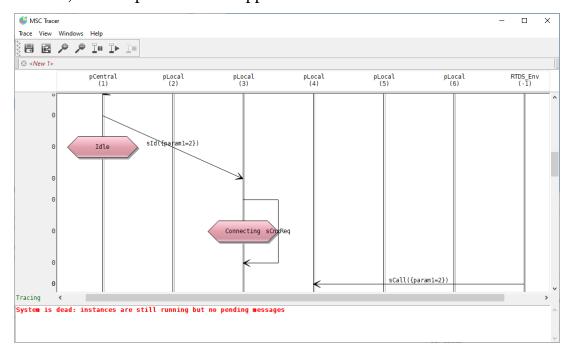




The "VIOLATED" in the "Result" field means that some problem has been found. To show the problem, the allows to extract a failing scenario, either as a MSC trace, or as a scenario that can be executed back in the simulator. Let's select the MSC trace:



The zone at the bottom of the trace says: "System is dead: instances are still running but no pending messages", so this is a deadlock: the system is in a state where nothing can happen any more, but instances are still alive and waiting for something. By going up the trace, we can spot what has happened:



The very first call was actually from one pLocal to itself, which is a case that is not handled correctly. So the pLocal instance is stuck in its "Connecting" state, waiting for



either "sCnxConf" or "sBusy", which will never come. After that, all other instances of pLocal have tried to contact it by sending a "sCnxReq" message, which will never be handled. So all instances are now stuck.

So we can see that even on a very simple system like this, validation can actually spot issues that weren't obvious at first sight. It can actually do much more than that, especially via properties that can be checked with the system. This is however out of the scope of this tutorial; for more information, please refer to the example Studio/Validation in the PragmaDev Studio distribution.

4.4 Conclusion

During this tutorial we have been through:

- Test of an SDL system,
- C code generation from an SDL system.
- Validation of the system using exhaustive simulation.

When it comes to design, the system will actually be implemented on a given target, so additional requirements will have to be taken into account:

- Use of legacy code and/or external libraries, usually written in C with no way to manipulate SDL's high-level abstract data types;
- Support for additional concepts, such as semaphores or pointers, unneeded in an SDL description, but usually required in real-time systems.

This is the aim of the SDL-RT language, which keeps the graphical description used in SDL but introduces the missing concepts required for low-level design.

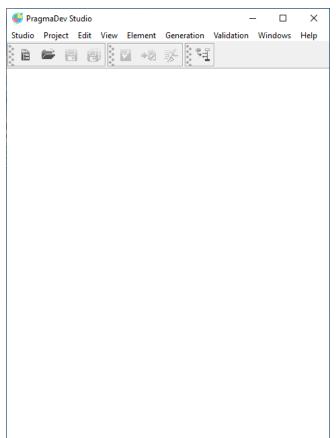
So let's move on to the PragmaDev Developer tutorial!



5 PragmaDev Developer Tutorial

5.1 Organization

Let's get our hands on the tool! Start *PragmaDev Developer* (or *PragmaDev Studio* if this will be the application you will be using).. The window that appears is called the Project manager:

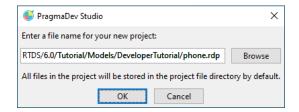


The Project manager window

The project manager gathers all the files needed in the project. First let's create a new project with the $New\ project$ button:

A window will pop up to set the project file name. Use the 'Browse button' to select the project's parent folder and file name:





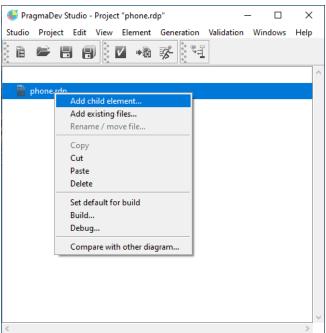
Let's set it to "phone":



phone empty project

5.2 Requirements

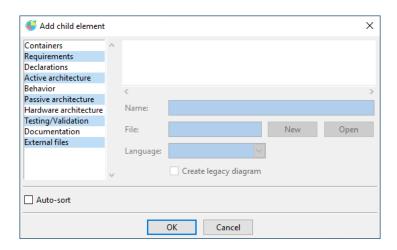
Let us express the requirements of our system as MSC. To add an MSC, select the project, and click on the right mouse button. A contextual menu will appear:



Add components to the project

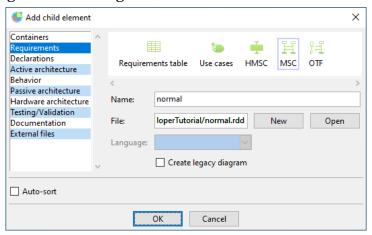
Select *Add child element* and the following window will appear:





The add component window

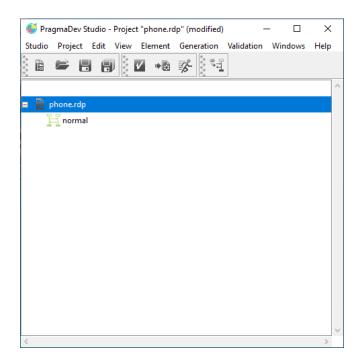
In the *Requirements* category, select MSC component and click on the *New* button. Go to the directory where your project is and type in "normal" with no extension. Click on save and you will get the following window:



Completed Add component window

Click Ok and the "normal" MSC appears in the "phone" project:

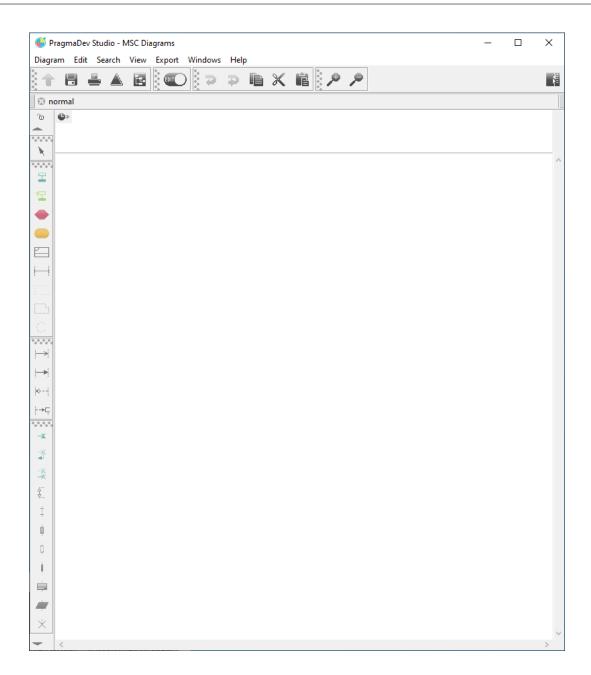




"normal" MSC in "phone" project

Double click on the MSC name or icon to open it. The MSC editor opens:

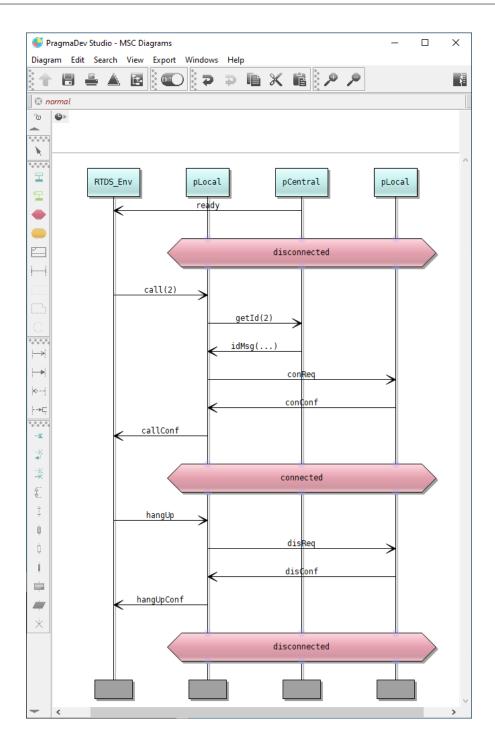




The MSC editor

Draw the following to express the requirements of our phone system:





The "normal" MSC

This MSC basically says the following:

- pCentral indicates the system has been initialized and is ready
- The initial global state is disconnected
- The user represented as the environment (RTDS_Env) makes a request on the first phone pLocal to call the phone with the number 2
- The first pLocal asks the central the queue id of the phone with number 2
- The first pLocal uses the id to send a connect request (conReq) to the second



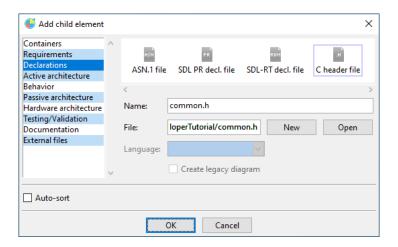
pLocal

- The second pLocal being disconnected, it confirms the connection (conConf)
- The first pLocal tells the environment the call has succeeded
- The global system state is then considered connected
- The user hangs up
- The first pLocal sends a disconnection request (disReq) to the second pLocal
- The second pLocal confirms disconnection (disConf) back to the first pLocal
- The first pLocal tells the environment the disconnection is confirmed
- The overall final state is disconnected

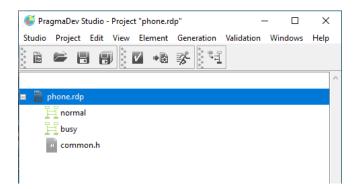
You can write some other MSCs to get clearer ideas on what you want to do. Note the instances represented on the MSC can be any type of agent or semaphore. Somehow you are roughly defining the first architectural elements. You can copy from the phone example "normal" and "busy" MSCs in the project to complete the description.

5.3 Design

Let us now specify and design the system. As for creating an MSC, select the project and add a C header file component:



Project will be like:

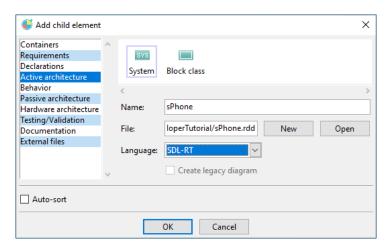


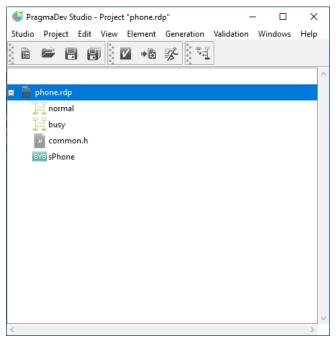


This header file will contain all type and macro definitions to use in the whole system. What we need is the number of phones that will be created and a type for the phone number. So open common.h and type its contents:

```
/* Number of phones to create */
#define NUM PHONE 5
```

Now, let us actually design the system itself. Select the project and add a System component. Make sure to select SDL-RT as the language for the system:

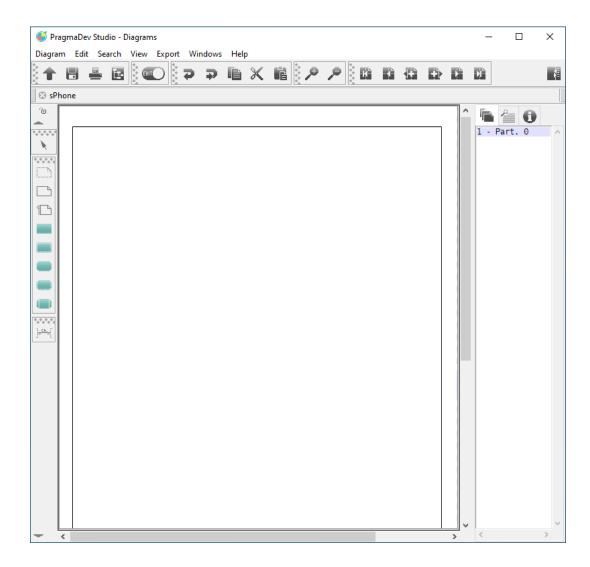




"phone" SDL-RT system in the "phone" project

Double click on the system name or icon to open the system diagram in the SDL-RT editor:



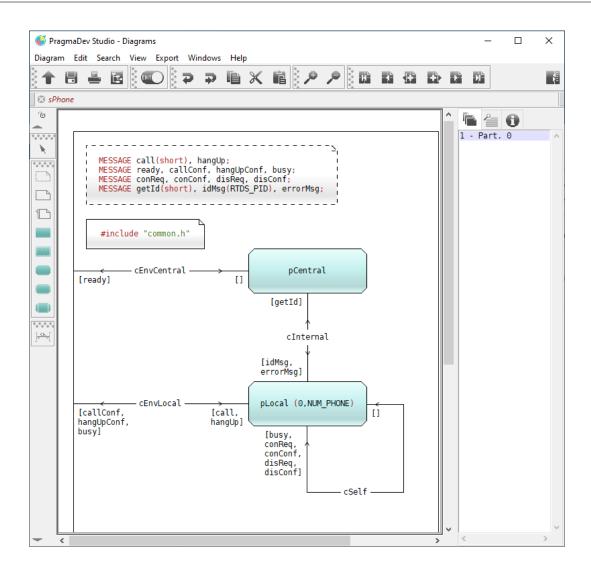


The SDL-RT editor

The system being very simple it will not require any block decomposition. The central will be a process as well as the phones. All the phones have the same behavior so they will be several instance of the same process. The phone system is therefore made of two processes. For better legibility their name will be prefixed by a 'p' because they are processes.

Note: to draw the cSelf channel keep the shift key down and click where the channel should break.





phone system view

Since pCentral is making the link between the pLocal processes and considering the number of phones can be modified, pCentral will create all instances of pLocal. To represent that, the name pLocal is followed by the initial number of instances and the maximum number of instances. Since the maximum number of instances is defined in common.h, we include it in a text box.

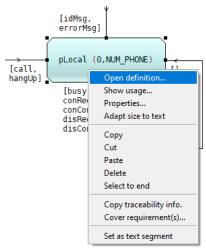
Messages to be exchanged between the processes are defined in the additional heading symbol and listed in the channels . To specify the incoming and outgoing messages in the diagram, click on the "[]" and type in between the square brackets. The channel going to the outer frame is implicitly connected to the environment. In the above example the channel cEnvLocal connects pLocal to the environment and defines call and hangUp as incoming messages and callConf, busy and hangUpConf as outgoing messages. The channel cEnvCentral connects pCentral to the environment and defines ready as an outgoing message. The cSelf channel has been created to represent messages exchanged between the different instances of pLocal.

In the message definitions, only the messages call, getId and idMsg have parameters. In our example process ids will be stored, so in order to design an RTOS independent



model the RTDS_PID type will be used. During code generation this type will be mapped to the real RTOS data type.

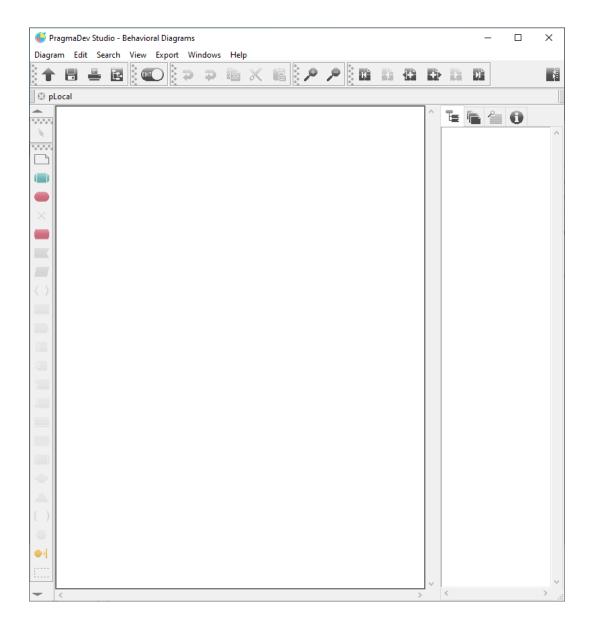
Select pLocal and click on the right mouse button to open the process definition, or simply click on the button that appears near the symbol when hovering the mouse pointer over it:



Contextual menu

Since the process is not in the project it will ask if it should be added. Answer yes and an Add child element dialog pre-filled with the process name appears. Click OK and you end up in a new windows showing the process definition.





The process behavior description in SDL-RT editor

The first thing to design is the start transition. It is what the process will do as soon as it is created. In the case of pLocal process we do nothing:



That transition means that once the process is started it will go to state idle. Note you can use automatic insertion in the editor: place a start symbol —, keep it selected and click on the state symbol in the tool bar —. The state symbol is automatically inserted and connected after the start symbol.

An internal data dictionary is updated on the fly to ease the writing of the process be-

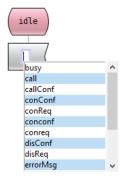


havior. First create the idle state definition: click on the State icon and put it at the top of your page:



The state name is in edit mode so you can directly type idle in it. Note that as soon as you start typing, PragmaDev Developer will display a list of choices for the state name, listing all those starting with the text you have already typed. To select one of the names, use the up and down arrow keys to browse the list, or click on it. Here, the list has only one entry because the idle state is the only one that has been defined so far.

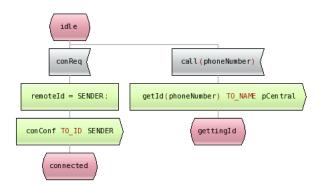
Once the state has been defined, click on the input symbol in the tool bar and the input message symbol will be automatically inserted below the state symbol. As for the state, the list of possible messages will appear as soon as you start typing. You can also press the F8 key to display the list of all possible messages:



Select the call message and complete it with the parameter as described below. This facility is context sensitive and works for messages, states, semaphores, and timers. You can now finish the state description by yourself as explained below.

Considering the requirements described earlier the pLocal process can either be asked to make a call by the operator or receive a call from another phone. The idle state can therefore receive two types of messages described below:

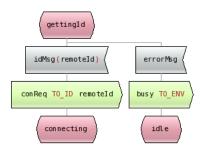




When receiving conReq message, it will reply conConf to the conReq sender. TO_ID and SENDER are SDL-RT keywords in the output symbol. The SENDER id is stored in remoteId variable. The process then goes to connected state.

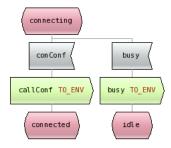
If asked to make a call, the phone number to call needs to be retrieved. To do so, a variable of the correct type is given as parameter of the receiving message. It will be assigned when this message is received. Since pLocal has no idea how to address a phone number it asks the central process the receiver queue id with the getId message. The phoneNumber variable is re-used as is and the TO_NAME SDL-RT keyword is used to specify the receiver. Note TO_ID PARENT could have been used since the central process is the current process's parent. The process then goes to gettingId state waiting for the central to answer. Note also that the memory allocated for phoneNumber memory will be freed by the receiver of the getId message.

Once the queue id of the remote phone is received from central, it is first stored in a local variable and the connection request message conReq is sent. The process then goes to connecting state. If the pid of the receiver was not found, the errorMsg message is received. The process tells the user (environment: TO ENV) and goes back to idle state:



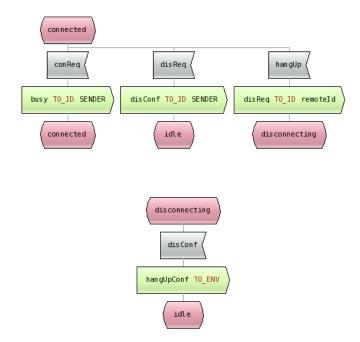
The remote process is either available and replies conConf, or not available and replies busy:





Depending on the answer the resulting state is different.

Now that you have understood the basics of the finite state machine you can complete the process behavior:



As the description is done, the browsing window on the right side is updated allowing to quickly jump to a transition: just click on the transition. This is especially useful when the system gets big.

```
(start)
connected
conReq
disReq
hangUp
connecting
busy
conConf
disconnecting
disConf
gettingId
errorMsg
idMsg
idle
call
conReq
```



It is now time to declare variables in our process. To do so the text symbol in the process behavior diagram is used with standard C declarations in it:



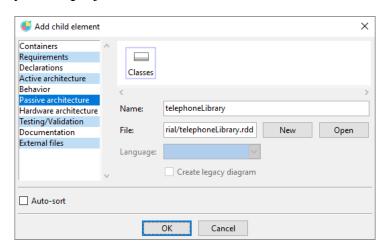
Note the types of the variables used in the input and output symbols: short for call and getId and RTDS_PID for idMsg. RTDS_PID is the type for a process identifier; It is mapped to the corresponding RTOS-dependent data type.

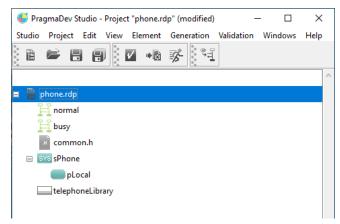
Let's have a look at process pCentral now. It must do the following things:

- at startup, it creates all instances of pLocal and gives them a new phone number;
- when asked for a phone number, it sends back the queue id for the corresponding process.

To avoid mixing the code managing the phone numbers with the code managing the processes, let's decide we'll use a class associated to pCentral that will take care of the phone numbers.

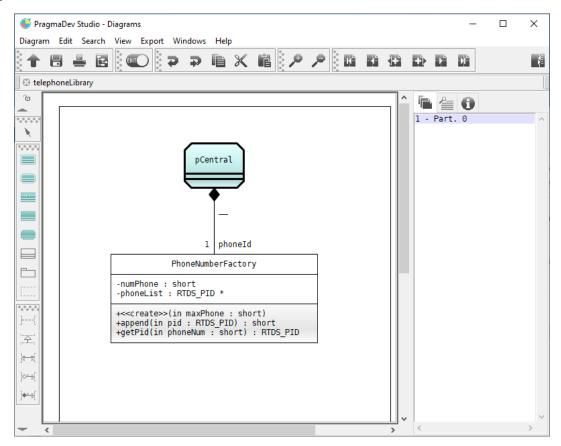
The first thing to do is to tell pCentral that it should use a class. So, let's go back to the project manager with the quick button and let's create a class diagram named telephoneLibrary in the project:







Double-click on the class diagram's name to open it and let's define a class associated to pCentral:



In a class diagram, the process pCentral is represented as an active class with a "graphical stereotype": the class symbol has bold borders and looks like a process symbol in a block diagram. Note the symbol used is a process symbol, not a process class symbol. That means the symbol is a direct reference to the process declared in the SDL system. The class PhoneNumberFactory is the class we will use to manage the phone numbers. Its interface is quite simple:

- Its constructor (named «create» in the symbol) will just initialize all internal data, it takes the maximum number of phones to manage;
- The append method will add a new phone to be managed.
- The getPid method will return the process id for a given phone number.

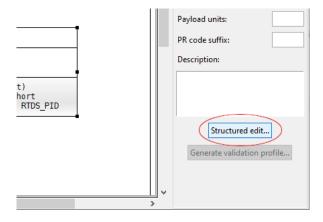
The class PhoneNumberFactory will also have 2 private attributes:

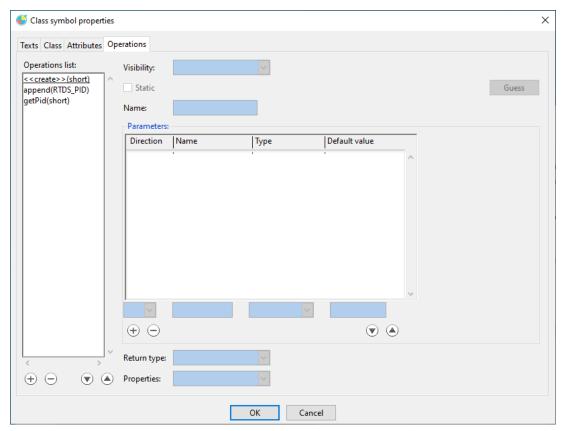
- numPhone is the next available phone number;
- phoneList is a pointer on a process id. The process ids will actually be stored in an array.

Since there will only be one instance of PhoneNumberFactory used only in pCentral, we can make the instance a part of the process via a composition with a cardinality set to 1. The role name phoneId will identify the instance of PhoneNumberFactory in pCentral. That means phoneId does not need to be declared in the SDL diagram; it is implicitly declared.



To fill in the attributes and operations, you can either type the text, or select the class, click on the right mouse button and select *Properties*. The symbol properties will appear in the zone at the right of the diagram editor. There, you can click the Structured edit button, which will open a dialog allowing to add all the attributes and operations in a graphical way:



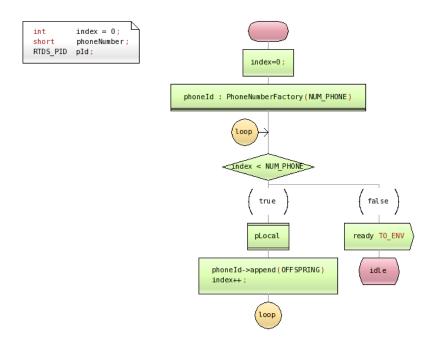


Now we have our class to manage the phone numbers. Of course, it isn't complete yet, since we didn't write any actual code for the methods. But its interface is fully defined, so we can go back to our pCentral process.

Go to the system diagram phone, and double click on pCentral. Since the process is not in the project it will ask if it should be added. Answer *yes* and a pre-filled save window



with the process name appears. Click *OK* and the process definition window appears. First, its initial transition:



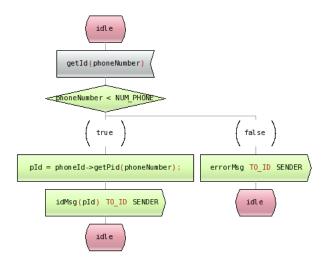
The first thing to do is to create the instance of PhoneNumberFactory we will use. This is done via an object initialization symbol, where the instance phoneId (the name we set in the role in the class diagram) is created as an instance of PhoneNumberFactory. The class constructor takes the maximum number of phones to handle as a parameter. Again, because of the association between PhoneNumberFactory and pCentral classes, phoneId is implicitly declared in pCentral SDL behavior diagram.

Then, all instances of pLocal are created in a loop testing index < NUM_PHONE. Each time the loop is executed the pLocal process is created and its process id (OFFSPRING keyword for the parent process) is stored in phoneId object via the append method.

After the pLocal processes creation, the ready message is sent to the environment to indicate initialization is finished and the process goes to state idle.

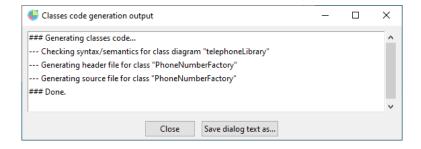
Note we have intentionally introduced a C syntax error by forgetting ";" in the lowest block of code to later show how to analyze the compiler errors.





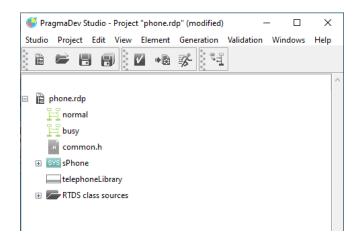
The only request that can be received by pCentral process is getId. The phone number to reach is the GetId parameter (phoneNumber). The process id of the phone is extracted with the getPid method. When received, the index corresponding to the received phone number is searched via the getPid method on the PhoneNumberFactory instance. The answer is sent to SENDER (SDL-RT keyword in output). If the phone number is out of range, an error message is sent back to the sender.

Now, let's go back to our class PhoneNumberFactory: we could write the .h and .cpp files directly, but PragmaDev Studio can help. So go back to the project manager, select the phone system, and select *Generate classes code...* in the *Generation* menu. A log window will then list the operations made during the code generation, which should run without errors.



Now let's close the log window and go back to the project manager:





RTDS class sources package has been automatically created and contains C++ code generated from the classes defined in the project.

RTDS class sources should contain the .h and .cpp files for the class PhoneNumberFactory. Open PhoneNumberFactory.h:



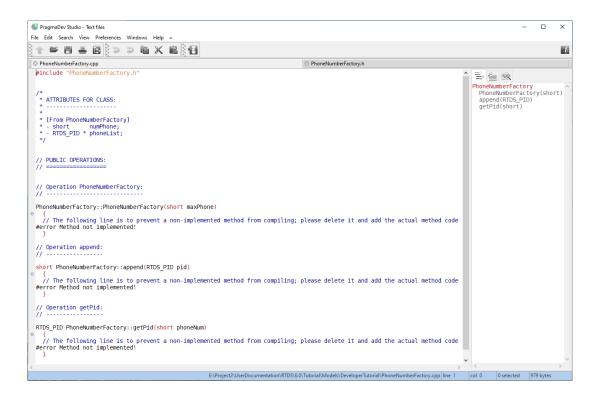
```
PragmaDev Studio - Text files
File Edit Search View Preferences Windows Help
  PhoneNumberFactory.h
          #ifndef _PHONENUMBERFACTORY_H_
          #define PHONENUMBERFACTORY_H_
           // Forward declaration (the following includes may use the class)
          class PhoneNumberFactory;
           // Standard and common includes
9
10
11
12
13
14
15
          #include "common.h"
#include "RTDS_gen.h"
          // Includes for related classes
          #include "RTDS_messages.h"
16
17
18
19
           // CLASS PhoneNumberFactory:
          class PhoneNumberFactory
             // ATTRIBUTES:
            private:
                            numPhone;
               RTDS_PID * phoneList;
             // OPERATIONS:
32
33
34
35
            public:
               PhoneNumberFactory(short maxPhone);
               virtual short append(RTDS_PID pid);
virtual RTDS_PID getPid(short phoneNum);
41
          #endif
E:\Project2\UserDocumentation\RTDS\6.0\Tutorial\Models\ line 1
                                                      col 0
                                                                0 selected
                                                                           614 bytes
```

Since the file common.h has been defined at the project level, it is supposed to be needed everywhere in the project. So it has been automatically included in the generated header file. RTDS_gen.h is a generated file containing declarations specific to the system. The class definition then contains all attributes and operations we entered in the class diagram.

Please note this header file must not be modified manually: it will be re-generated each time a code generation is made.

Now open PhoneNumberFactory.cpp:





Skeletons for the constructor and the two methods defined for PhoneNumberFactory have been generated, all containing a "#error" precompiler directive to make sure they won't compile, since an implementation is now supposed to be written for them.

Note the C++ code browsing window on the right to quickly access operation definitions. The generated code also includes the attributes definitions as a comment.

Now you can enter the code for the methods:



```
PragmaDev Studio - Text files
File Edit Search View Preferences Windows Help «

↑ □ □ □ □ □ □ × □
                                                                                                                PhoneNumberFactory.h
         #include "PhoneNumberFactory.h"
                                                                                     PhoneNumberFactory
                                                                                      PhoneNumberFactory(short)
          * ATTRIBUTES FOR CLASS:
                                                                                      append(RTDS PID)
                                                                                      getPid(short)
          * [From PhoneNumberFactory]
          * - short
            short numPhone;RTDS_PID * phoneList;
          // PUBLIC OPERATIONS:
16
17
18
19
          // Operation PhoneNumberFactory:
         PhoneNumberFactory::PhoneNumberFactory(short maxPhone)
            numPhone = 0;
23
24
25
26
            phoneList = (RTDS_PID *)RTDS_MALLOC(maxPhone * sizeof(RTDS_PID));
27
28
          // Operation append:
         // -----
         short PhoneNumberFactory::append(RTDS_PID pid)
           phoneList[numPhone] = pid;
           numPhone++;
            return (numPhone-1);
         // Operation getPid:
38
39
40
         RTDS_PID PhoneNumberFactory::getPid(short phoneNum)
            return phoneList[phoneNum];
 E:\Project2\UserDocumentation\RTDS\6.0\Tutorial\Models\DeveloperTutorial\PhoneNumberFactory.cpp line 43
                                                                                   col 0
                                                                                           0 selected
                                                                                                      979 bytes
```

numPhone represents the next available phone number. The append method stores the process id in the phoneList array with index numPhone.

Please note that once the .cpp file exists, it will not be overwritten by the next code generation. So the code you've written will be kept as long as you don't manually erase the file.



5.4 Running the system

In the current release, execution and debug of the system can be done using:

- Posix and gdb integration on Linux or Solaris, or
- Win32 or FreeRTOS and MinGW integration on Windows, or
- CMX RTX and Tasking Cross View Pro debugger on Windows, or
- · OSE and gdb debugger on Windows, or
- Wind River Tornado environment on Windows or Solaris, or
- Nucleus and gdb debugger on Windows.

It is important to understand integration is done at two different levels:

RTOS integration

The generated code is based on C macros that are defined in the "Code template directory" to call the corresponding RTOS system primitives. Currently there is a directory for:

- FreeRTOS.
- Win32,
- Posix,
- CMX RTX,
- OSE Delta,
- OSE Epsilon
- ThreadX,
- uITRON 3,
- uITRON 4,
- VxWorks,
- Nucleus.
- Debugger integration

To be able to trace execution, set breakpoints and view variables, the *SDL-RT* debugger is interfaced with a C debugging environment. Depending on the C debugger functionalities there might be differences in the *SDL-RT debugger*. The available C debugger interfaces are:

- gdb (Gnu debugger)
- MinGW (Minimalist GNU for Windows)
- Tasking Cross View Pro

Tasking integration has one major restriction: it is not possible to send an SDL-RT message to the running system from the debugger.

XRAY

As with *Tasking* integration: it is not possible to send an SDL-RT message to the running system from the debugger.

Tornado



- Multi 2000

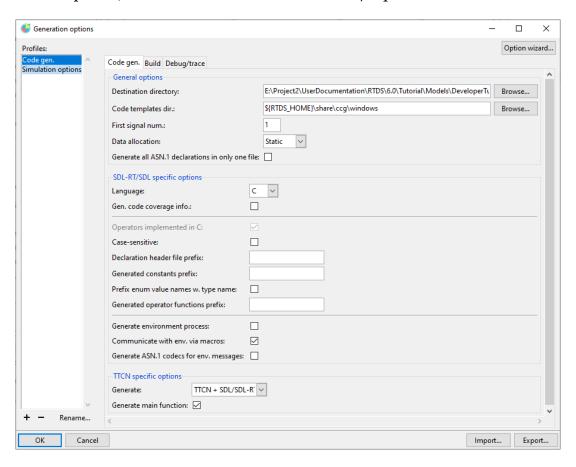
As with Tasking and XRAY integrations, it is not possible to send an SDL-RT message to the running system from the debugger.

The rest of the tutorial will use your host environment as a target (windows or posix integration) and gdb as a debugger. There is no need to install another tool as we will use the ones provided in PragmaDev Studio distribution (gdb and MinGW).

Please note win32 and posix integrations use a socket to communicate with the host. The default port set to 49250 but it can be modified in the *Socket port num* field of the corresponding generation profile.

5.4.1 Generation profile

Now that the system is designed, let's debug it with the SDL-RT debugger. To do so we will need to generate code from the SDL-RT system. This requires to define a set of generation options, which is done via the *Generation / Options...* menu:



Rename the default empty profile and use the *Options wizard* to quickly set up a working profile:

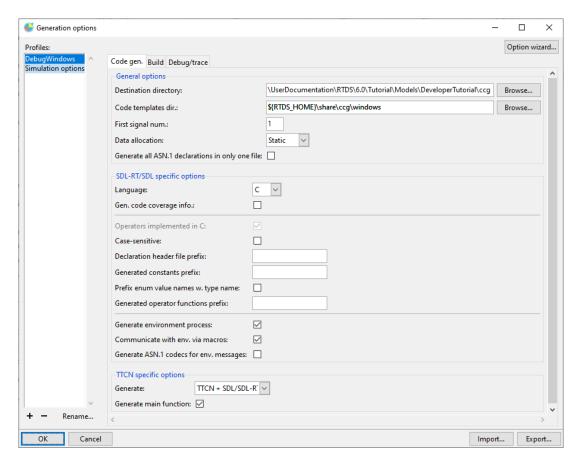




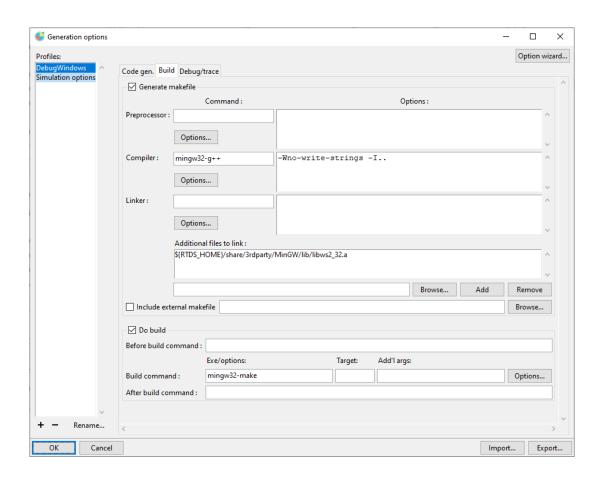
You'll have to check that everything is setup properly:

- The destination directory should be set to ccg, in the project's parent directory. This should be the default. This directory will be created if it doesn't exist yet, so no need to create it explicitely.
- Since we're using C++, we checked the "Use C++ compiler" in the wizard dialog. Make sure the compiler is actually set to "mingw32-g++".
- Make sure the C++ include path option includes the upper directory because the common.h file is in the project directory and the generated C files are in ccg. So the compiler options must include "-I..".

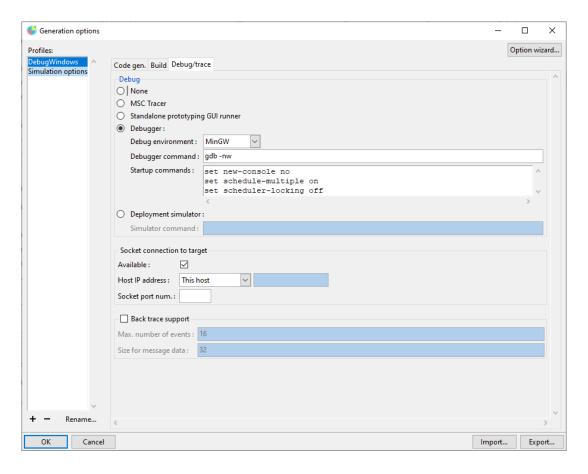
Here is how the 3 tabs should look like in the final set of options:









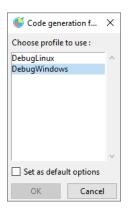


Gnu example on Windows platform

5.4.2 Compilation errors

Once the SDL-RT debug profile is properly defined select the phone system in the Project manager and click on the Debug quick button in the tool bar:

If several execution profiles are defined, as in the examples, a window pops up asking for the profile you want to use:

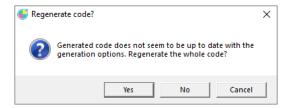


The first time, the tool will ask about the target directory:



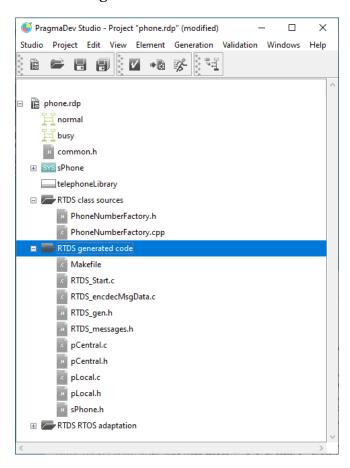


PragmaDev Studio will compare the dates of the generated C/C++ files with the dates of the project, the diagram, the preferences. If the generated C file are not up to date the following window will pop up to confirm the code should be generated again or not.



This is very useful with large projects to avoid long compilations.

The package RTDS generated code is automatically created in the Project manager window that will contain all the generated C files.



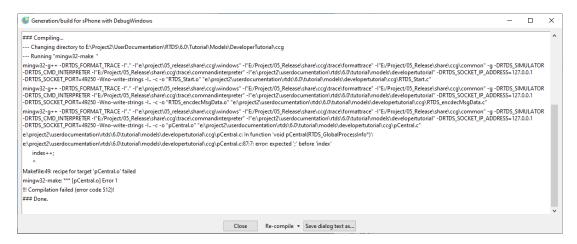
The package RTDS RTOS adaptation is also automatically created in the Project manager window; it will contain all the C files needed to adapt to the selected RTOS. These



files are actually in the code templates directory defined in the generation profile. These files are normally not needed but since they are part of the build process they must be visible.

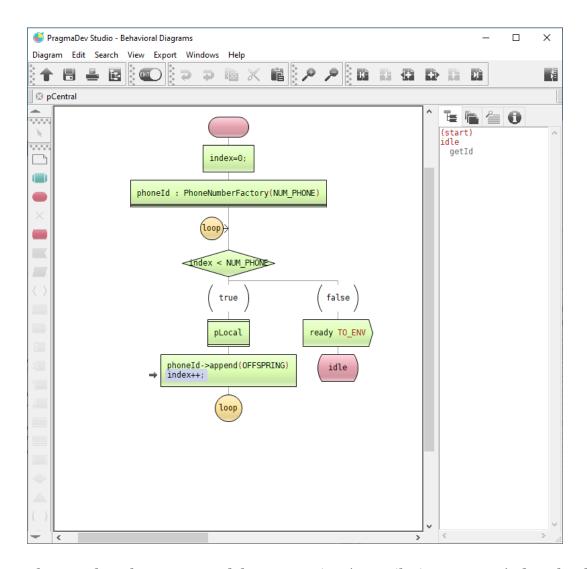
The package RTDS class sources is also re-generated, but all the existing .cpp files are left as is.

Syntaxic verification, semantic verification, code generation, and compilation starts: Let's consider an error occurred while designing pCentral process. The compiler will complain in the *Generation / compilation output* window:



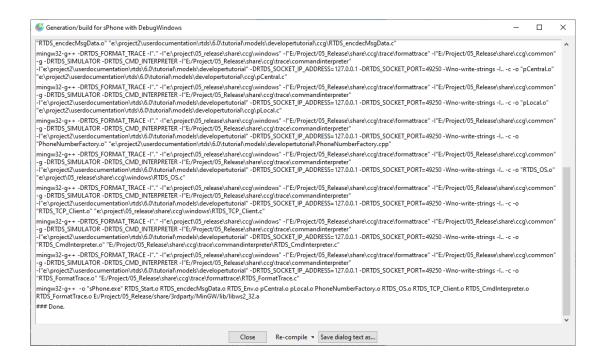
Double click on the desired warning or error to automatically open the SDL-RT editor on the error (please note this might not work when using another compiler than a gcc based compiler):





Once the error have been corrected the *Generation / compilation output* window should look like this:

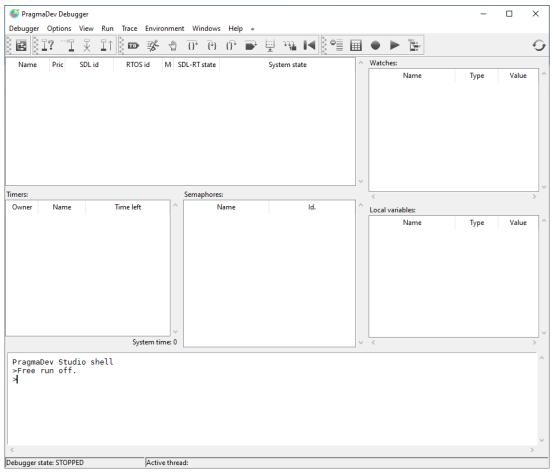






5.4.3 The SDL-RT debugger

When launched, the SDL-RT debugger will automatically start and initialize the underlying gdb environment. The *SDL-RT debugger* window is started automatically:



The SDL-RT debugger window

The SDL-RT debugger is basically a debugger with graphical integration. This window provides snapshots of the overall system.

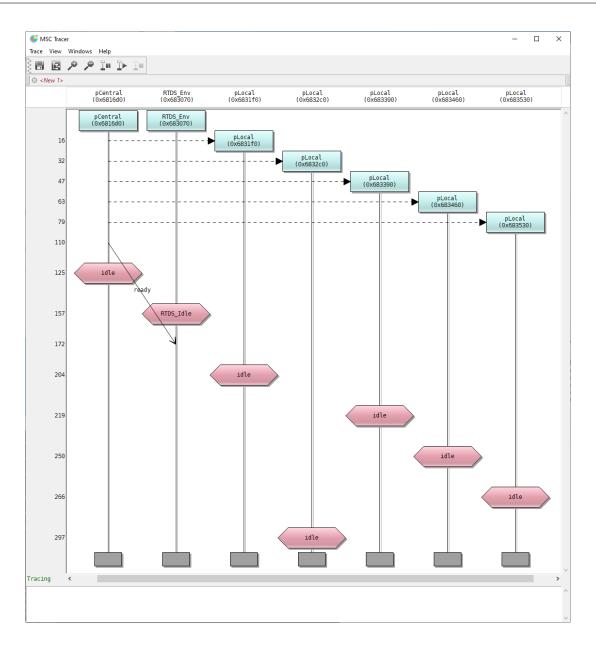
First we want an MSC trace to see what is happening in the system. Click on the *Start* MSC trace quick button:

An *MSC Tracer* window appears. Note it is not an MSC editor window; the MSC Tracer has been optimized for performance and the displayed trace can not be edited.

Let's start the system; click on 'run' quick button:

Let the system run until all pLocal processes are created by pCentral and their start transition executed:





MSC trace

Note you can detach the execution button bar by dragging it away from the debugger window by its header (the zone looking like this: - if you don't see it, go to the preferences in the "Studio" menu of the project manager, and check the option "Detachable toolbars" in the "General" tab).



The environment is represented by RTDS_Env process. It is automatically generated by PragmaDev Studio when debugging to represent all external modules. When generating target code it will of course disappear.

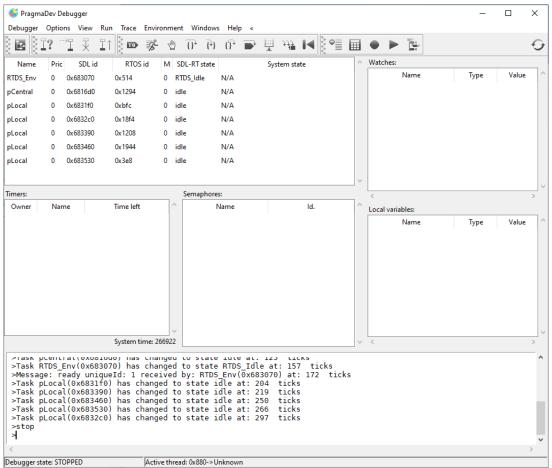
Process pCentral dynamically creates 5 instances of pLocal, sends ready message to



the environment and goes to idle state. Each pLocal instance then go to idle state. On the left is the value of the system time.

Click on the Stop button to break execution:

The SDL-RT debugger window shows the list of processes with their names, priority, process id, queue id, number of messages in their respective message queues, SDL-RT internal state as we defined in the diagrams, and the RTOS internal system state if available.



SDL-RT debugger window

It can also display information regarding semaphores and timers, local variables and watch variables. The SDL-RT debugger shell gives a textual trace of the events displayed in the MSC.

We are now going to set a breakpoint, simulate a user using one phone to call another one and step in process pCentral.

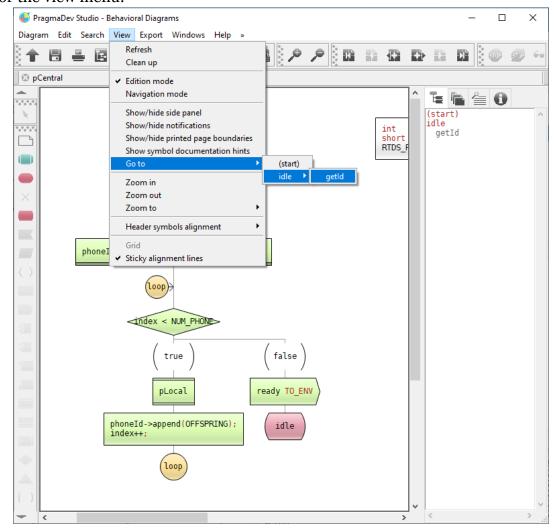
Let's put a breakpoint in pCentral process. To do so:

- Open pCentral process from the *Project manager*. Double-clicking on its name in the running instances list in the debugger window works too.
- Go to transition getId in state idle using the *transition browser* window on the right:





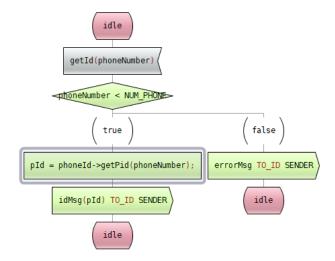
or the view menu:



The *transition browser* of the *View/Go to* menu will list all SDL-RT states and all transitions in each state to quickly navigate through the system. In our case there is only one state and one transition.

• click on the symbol just after the decision:



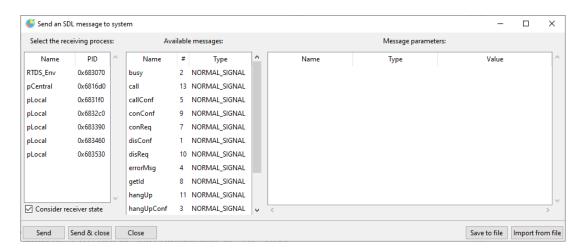


• click on [©] or go to *Debug / Set breakpoint* menu in the *SDL-RT editor*. A breakpoint symbol will be displayed on the side of the selected symbol:



We will now simulate an incoming message from a user. Please note this feature is not available in the *Tasking* integration nor in the *XRAY* integration because these C debuggers can neither execute function calls on target nor simulate interrupts.

- Go to the *SDL-RT debugger* and click on "Send an SDL message to the running system" quick-button
- The Send an SDL message window shows up:

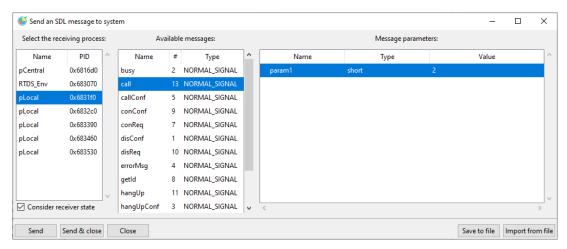


Send an SDL message window

On the left are listed all possible receiving processes, in the middle all possible messages, i.e. all messages used in the SDL-RT system, and on the right the value of the parameters associated with the selected message.

Prepare the message to be sent:

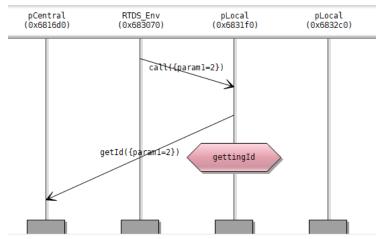




The message to be sent is call, with the parameter value 2. We will choose the first listed instance of pLocal as the receiver. You might want to write down it's PID, since we will send it another message later.

NB: it may happen that the first listed instance of pLocal has been assigned the phone number 2, in which case the following will not work, as the phone will try to call itself. If this happens, just send again a new call message to another pLocal instance.

- Click on Send & close button.
- Click on Run in the SDL-RT debugger window,
- The following trace appears in the MSC:

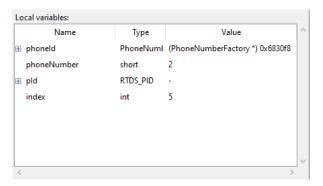


 The SDL-RT editor pops up where the breakpoint was set with the break line selected and an arrow in front of it:



The values of the process local variables are automatically displayed in the SDL-RT debugger. For example the phoneNumber variable value is 2:





Local variables values

- Click on *Auto step until next graphical symbol* button: That quick button will actually step in the C code until the line in the C file is generated from a graphical symbol. In our case it will only step once.
- The SDL-RT has moved to the next symbol:



• Click on Step over button: $\overline{\{\}^*}$

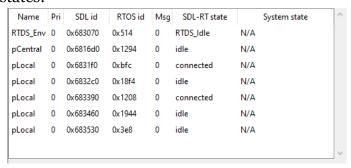
This will step in the C code as any normal C debugger. The text editor opens and displays the next line to execute in the generated C file. Have a look at the generated code to see how legible it is.



```
PragmaDev Studio - Text files
File Edit Search View Preferences Windows Debug Help «
RTDS TASK ENTRY POINT()
                                                  /* Double switch state / signal */
RTDS_transitionExecuted = 1;
switch(RTDS_currentContext->sdlState)
                                                        1
/* Transitions for state idle */
case RTDS_state_idle:
    switch(RTDS_currentContext->currentMessage->messageNumber)
                                                                       {
/* Transition for state idle - message getId */
case RTDS_message_getId:
RTDS_MSG_RECEIVE_getId( phoneNumber);
if ( !(phoneNumber < NUM_PHONE) )
                                                                                    RTDS_MSG_QUEUE_SEND_TO_ID(RTDS_message_errorMsg, 0, NULL, SENDER);
RTDS_SDL_STATE_SET(RTDS_state_idle);
break;
                                                                             else if ( phoneNumber < NUM_PHONE )
                                                                                     If
pId = phoneId->getPid(phoneNumber);
RTDS_MSG_SEND_idMsg_TO_ID(SENDER,
RTDS_SDL_STATE_SET(RTDS_state_idle);
                                                                                                                                                                                                                                                              pId);
                                                                                    break;
                                                                             RTDS transitionExecuted = 0;
                                                                } /* End of switch on message */
break;
                                                       default:
   RTDS_transitionExecuted = 0;
                                                             /* *(RTDS_HOME)/share/ccg/windows/bricks/RTDS_Proc_end.c begins */
/* $(RTDS_HOME)/share/ccg/windows/bricks/RTDS_Proc_end.c begins */
/* PragmaDev RTDS win32 integration */
/* PragmaDev RTDS win32 integration the state of the 
                                          */
RTDS_TransitionCleanUp( RTDS_currentContext, RTDS_sdlStatePrev );
} /* End of if ( RTDS_currentContext->currentMessage != NULL ) to execute transition */
} /* End of for ( ; ; ) */
                                     /* $(RTDS_HOME)/share/ccg/windows/bricks/RTDS_Proc_end.c ends */
                                                                                                              E:\Project2\UserDocumentation\RTDS\6.0\Tutorial\Models\DeveloperTutorial\ccg\pCentral.c | line 189 | col 0 | 0 selected
```

Note it is possible to switch from the SDL source to the generated C source back and forth with the *Search / Go to generated source* and *Search / Generated* code <-> source menus.

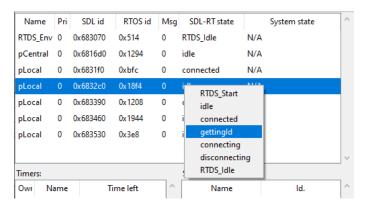
- Let the system finish its job: click on Run button.
- Stop the system once it has finished execution: \Box . The process list is updated with their new states:



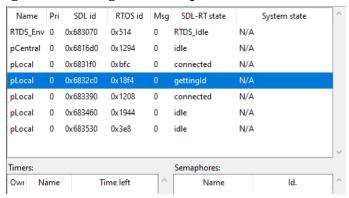
Two instances of the pLocal process are connected.

• It is also possible to change the state of a process. To do so right click on the state you want to change and a drop down menu will list all possible states. Let's change the state of the last instance of pLocal to gettingId for example:



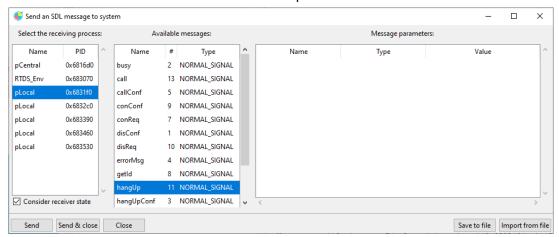


The state is changed on the target and the process list will refresh:



It is recommended to be cautious when changing a task state that way...

• We will now disconnect the 2 instances of pLocal. Click on the Send button ::



Select the hangUp message with the receiver set to the same pLocal instance as you selected as the receiver of the call message earlier (check with its PID). Then click on Send & close.

• We will now use the key SDL-RT event stepping button:

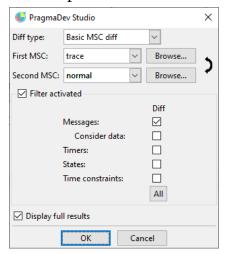
This feature runs the system until the next SDL-RT event such as sending or receiving a message, changing SDL-RT state, starting or cancelling a timer... Click on the button and you will see the system executing until the next SDL-RT event and then stop. This is a very nice feature when debugging for the first time.



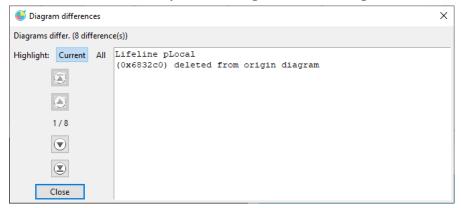
5.4.4 Verifying the behavior

We will now check if the behavior is the one we expected in the first place. To do so we will use the MSC diff feature.

- Once the execution is finished, close the MSC Tracer and save the trace.
- Go to the Project manager and open the trace.
- Go to the *Diagram / Compare with other diagram...* menu to get the MSC Diff configuration window and set it up as described below:

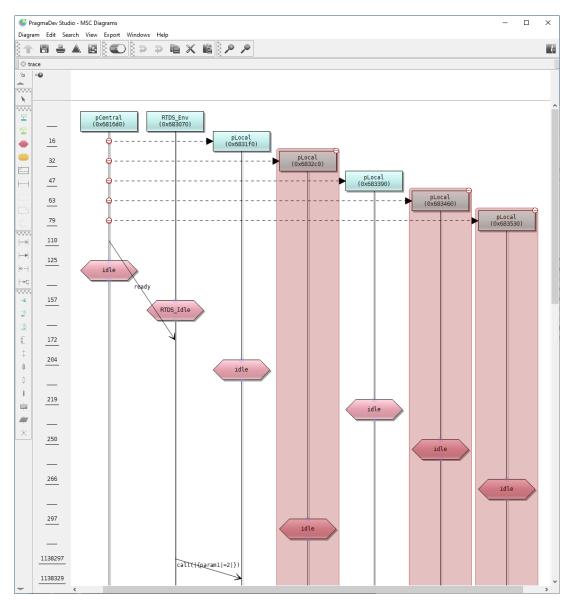


The first MSC is the execution trace and the second MSC is the normal MSC we have written in the first place. Since normal MSC was not supposed to be thoroughly detailed we will only show and compare messages without considering their parameters. Click Ok and you should get the following:



Here you can navigate through the differences, and by selecting All, then all of them will be shown in the diagram:





The differences between the MSCs are the dynamic task creation of the pLocal instances. After that the exchange of messages are the same between the dynamic trace and the specification. The SDL-RT system is therefore conform to the normal MSC specification.

You are done with a very simple SDL-RT debugging session. If you want more, do your own system or run the examples delivered in the distribution to see how to manipulate:

- timers,
- · semaphores,
- external C header files,
- · global variables.

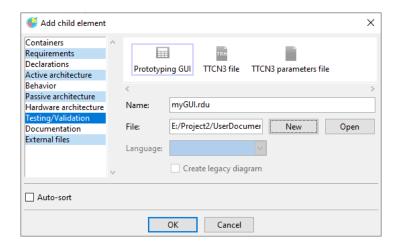


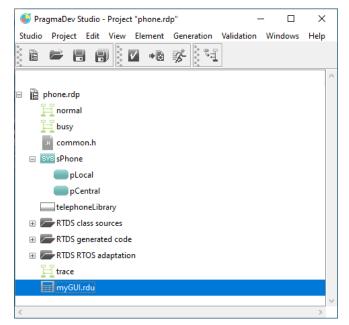
5.5 Prototyping GUI

PragmaDev Studio has a built in support to design simple prototyping interface to ease testing. We will build a very simple one for our phone system to demonstrate its capabilities.

5.5.1 GUI editor

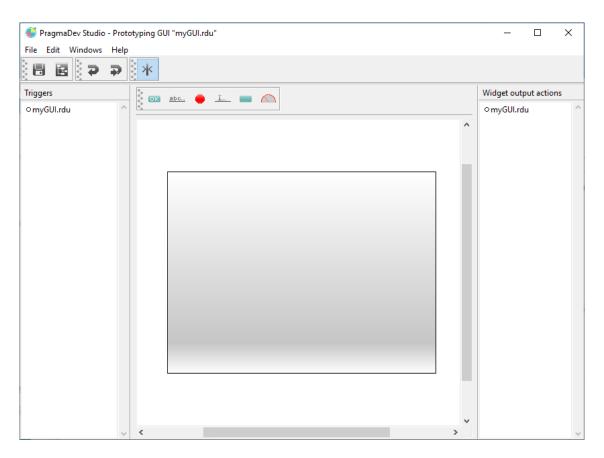
Add a Prototyping GUI node in the project and open it:



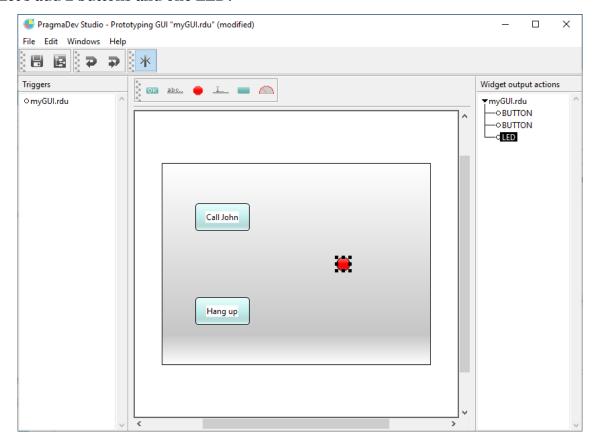


The left panel contains the incoming triggers for the GUI, the central panel the GUI itself, and the right panel the outgoing message from the GUI:



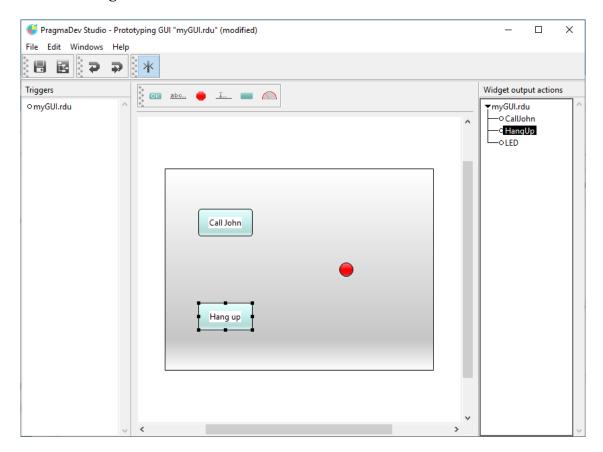


Let's add 2 buttons and one LED:

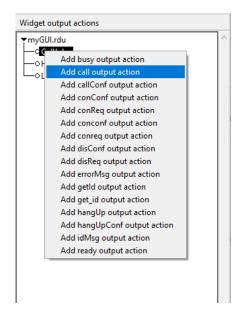




Change their display value in the central panel and their widget name in the right panel in order to recognize them:

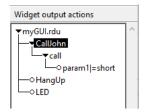


Let's say that when the user clicks on the "Call John" button, the GUI sends a call message with parameter set to "2". Select the Call John widget on the right panel and right click:

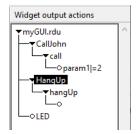




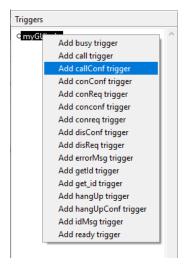
All the available messages in the system are then listed. Select call and expand the created sub-tree. The parameters are listed with their corresponding type:



Let's say the parameter value is '2' and let's send hangUp without any parameter when clicking on Hangup:



On the left panel now, we will add a new trigger. A trigger performs some action on the widgets whenever a message is sent out of the system. Select the top of the tree and right click to get a list of all the possible triggers:

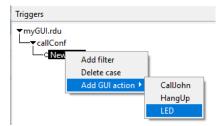


Let's add the callConf trigger. When a trigger is received by the GUI, a case with a set of filters is verified. Let's add a new case:

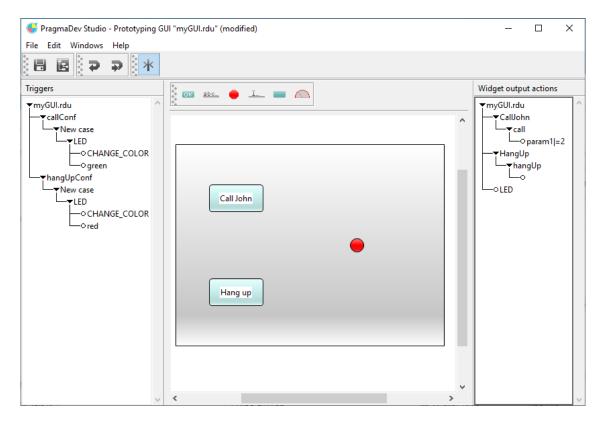




In our case we won't put any filter, we will just change the color of the LED:



The default action is DISPLAY; you'll have to right click on it to change it to CHANGE_-COLOR. The node in the tree under the action specifies the new color for the widget. It is possible to directly name the basic colors, otherwise the RGB hexa code can be used (e.g #FF8000 is this color). Let's put the LED back to red when we receive a HangUp confirmation and we're done:

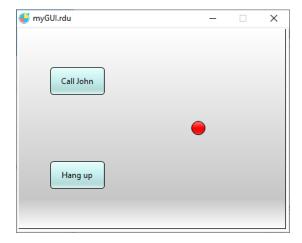


5.5.2 GUI simulation

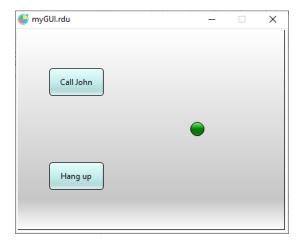
Let's start the Debugger again and click on the Start prototyping GUI quick button:

The GUI will start and connect automatically to the system:





Start an MSC trace and run the system. Click on the "Call John" button, that should send the call message with parameter value set to 2, the callConf should be received by the GUI, and the LED should be set to green:



For a more advanced GUI, please have a look at the AccessControl system in the Developer example directory.

5.6 Conclusion

During this tutorial we have been through the basics of the following:

- SDL-RT;
- · Project manager;
- SDL-RT editor;
- MSC editor;
- Code generation;
- SDL-RT debug including the three stepping modes:
 - SDL-RT key event,
 - SDL-RT graphical,



- textual;
- Conformance checking;
- · Prototyping GUI.

As a result you saw SDL-RT has the preciseness of C language with the graphical abstraction of SDL and UML perfectly suited to real time systems showing key concepts such as tasks, semaphores, timers, messages in a single consistent development environment.

Now it is time for you to work on a real real time system!



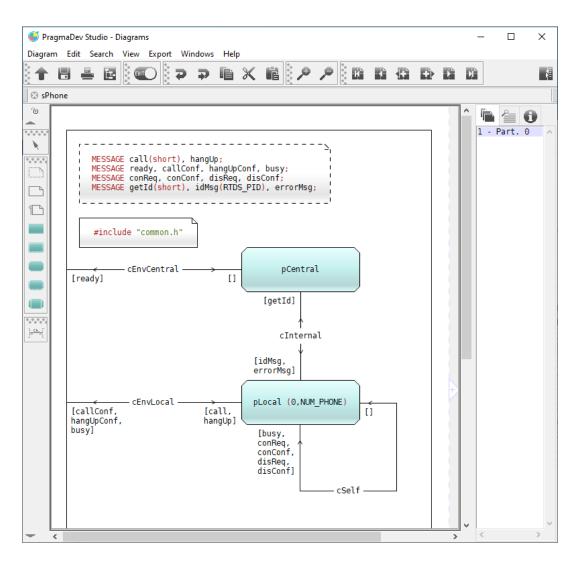
6 Automatic documentation generation

Let's now have a look at how to document our system. PragmaDev Studio has an automatic documentation generator that generates OpenDocument (OpenOffice), RTF (Microsoft Word), HTML, and SGML documents. In this tutorial we will generate an OpenDocument as it is very similar to generating an RTF document. The basic idea is to document while you are modeling your system in SDL, and when you are done just generate the documentation for a word processor or a browser.

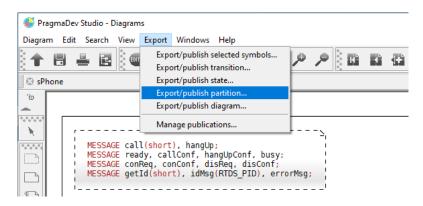
6.1 Publications

Let's first define what is important to document in our system and put it in a publication. For example let's consider the architecture of the system should be further documented:



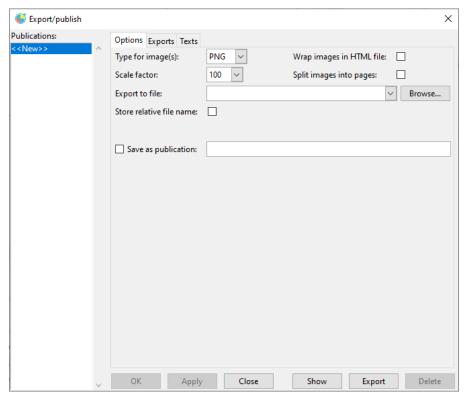


Get to the corresponding diagram and go to the *Export* menu. We want to export the whole partition, so select *Export/publish partition*...

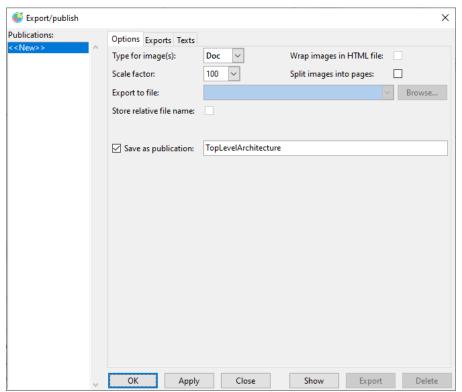




The *Export/publish* window opens:



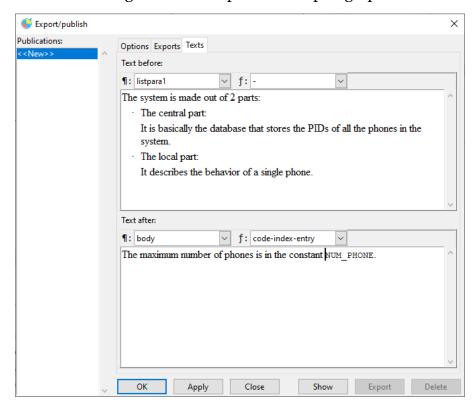
Let's give our publication a name, the *Doc* type, and check the *Save as publication* box:



Select the *Texts* tab. The two editors here allow you to type the texts that will be generated before and after the diagram when generating the documentation. Let's type a few



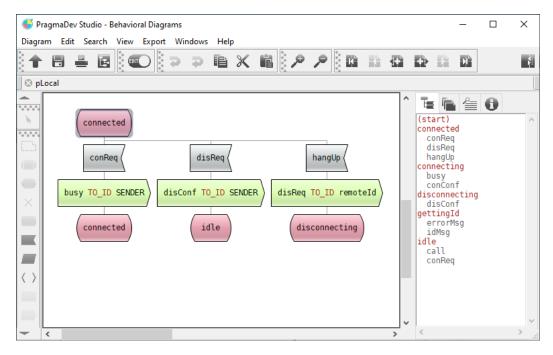
words to document the diagram with the pre-defined paragraph and character styles:



We want the NUM_PHONE identifier to appear as code, and also to be listed in the document index. To do so, select the text, and apply to it the code-index-entry character style that is listed in the "f:" selector above the text.

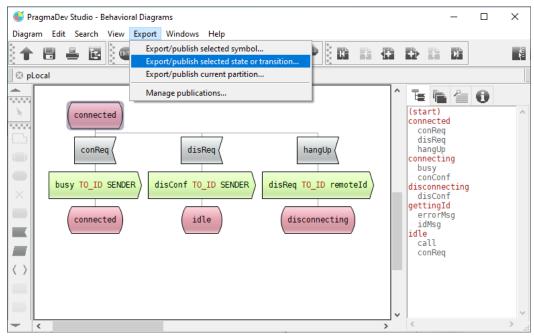
When done click OK.

Let's now document a transition. Open the pLocal process and go to the connected state:

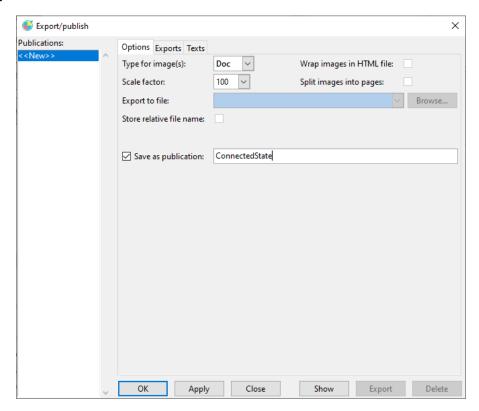




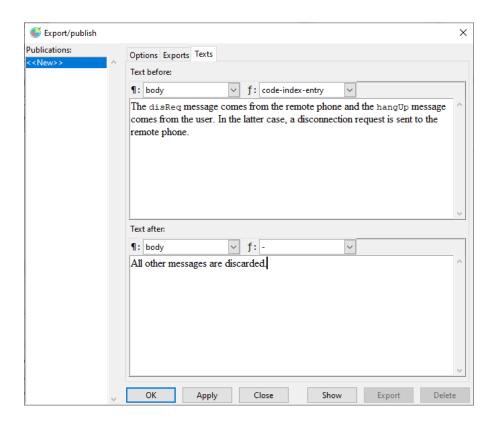
Go to the *Export* menu and select *Export/publish selected state or transition...*:



This will export the state with all the connected inputs as a publication. Let's document the state:



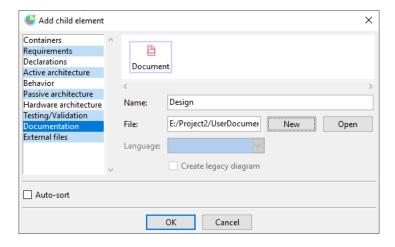




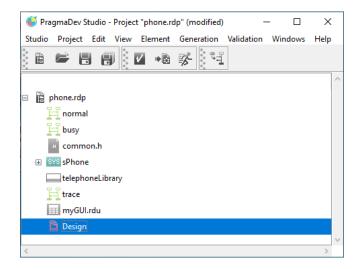
Please note the publications are saved within the diagram so it is important to also save the diagrams.

6.2 Documentation

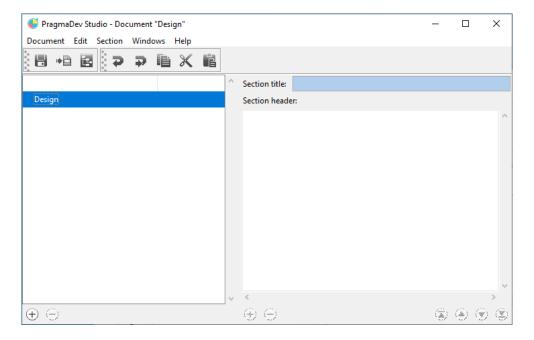
Let's now go back the *Project manager* and create a new item of type *Document*:





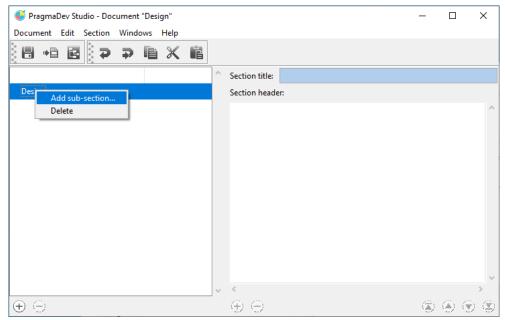


Let's open the *Document* Design:

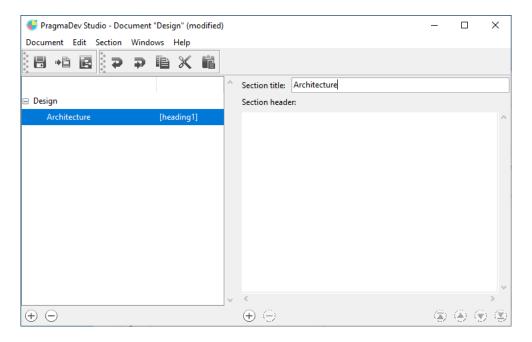




Select Design and right-click to add a sub-section, or click on the "+" button under the section list on the left:

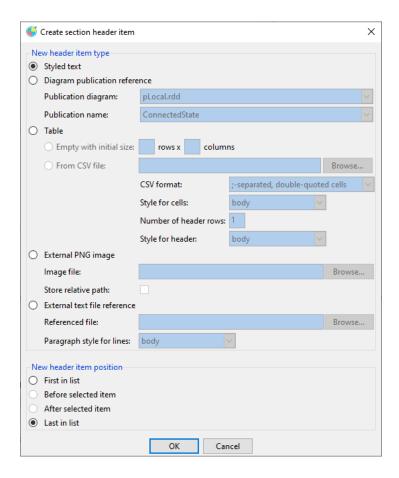


This sub-section will actually be the first chapter of the generated documentation. Adding other sub-sections at the same will generate other chapters. Adding sub-sections to this section will generate sub-chapters. Let's type the section title and add some contents to the section with the "+" button under the "Section header" zone on the right side:



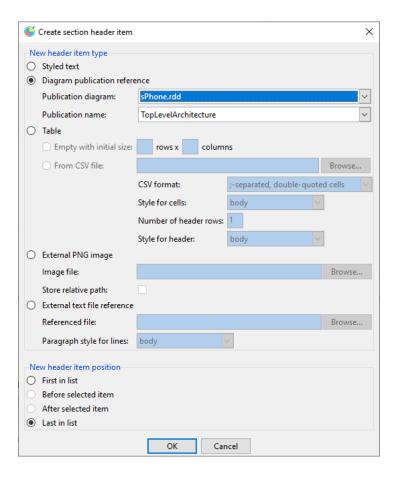
In order to have the *Diagram publication reference* available, the diagrams containing publications must be opened. So in our case the top level architecture diagram and the pLocal process should be open in order to move on. After clicking the "+" button, the following window will pop up:



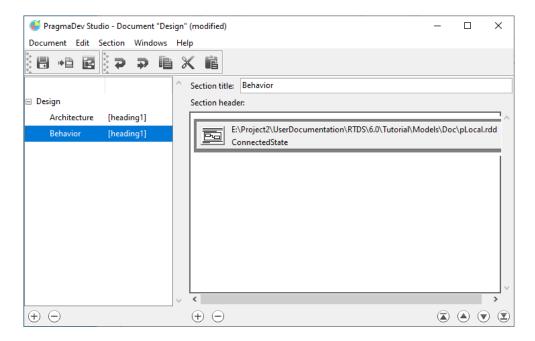


The *Styled* text allows to insert plain text in the documentation. To insert one of the diagram publication, select *Diagram publication reference*. The window should then look like this:





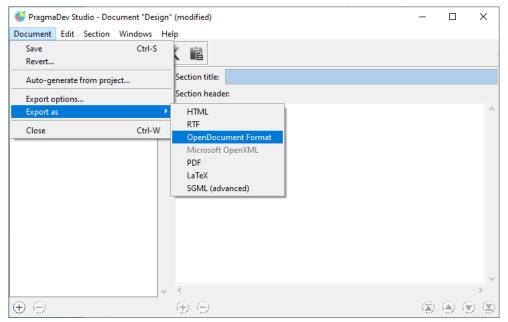
Select the appropriate *Publication diagram* and *Publication name* to insert in the document. Then create another sub-section in the document with the other publication:





6.3 Automatic generation

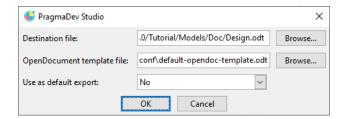
Go to Document / Export as / Open Document Format:



An OpenDocument is actually a zip file that contains several files among which:

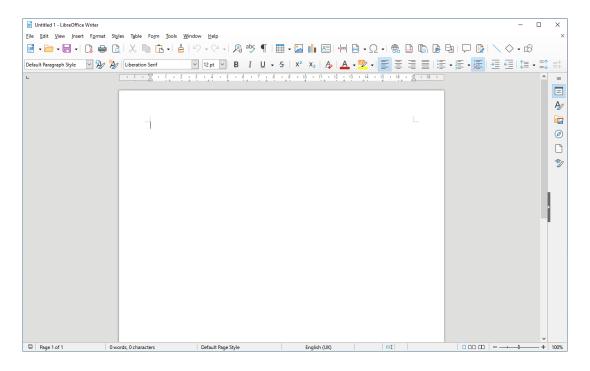
- one is the document itself as an XML file,
- one describes the styles used in the document also as an XML file.

In order to generate the full OpenDocument zip file, PragmaDev Studio requires a template file. There is a default one in the Studio distribution that will work fine, so you don't have to change it:

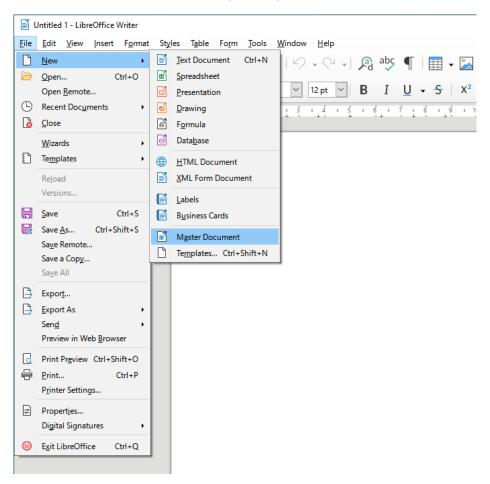


Now we will create an OpenDocument container for our generated document in which we can set a title, introduce a table of contents, and an index. To do so, let's start Libre-Office:



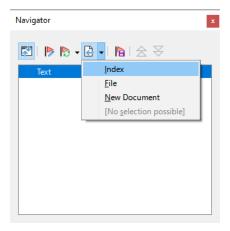


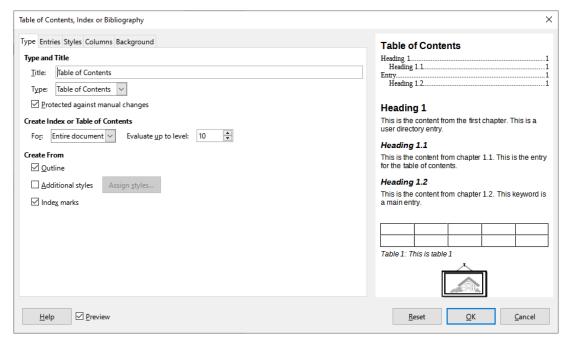
Create a new Master document with File / New / Master document menu:



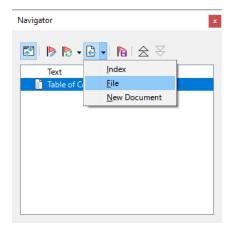


Type the title, insert a page break, and insert a table of content with the *Navigator* window:



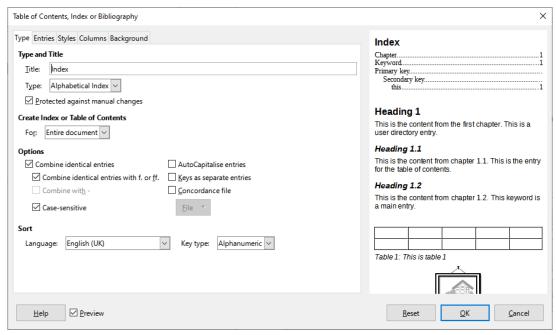


In the same Navigator window, insert the OpenDocument we have just generated:

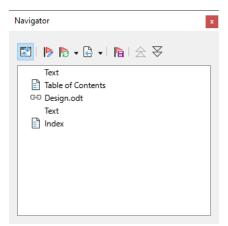




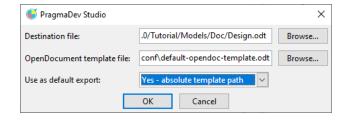
And insert an index:



It is possible to drag and drop sections in the Navigator window to get the right order:

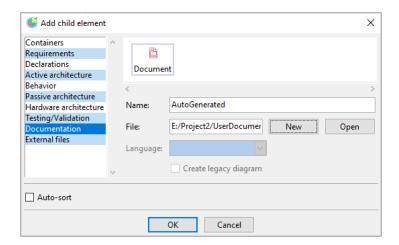


It is possible to add other sections or other external documents in the master document. When you further document your system, to update the generated documentation: open your Pragmadev Studio document, export it as an OpenDocument, replacing the existing one, and that's it! The OpenOffice master document will be updated by itself as well as its table of contents and index and ready to be printed. You can also set the OpenDocument export as the default one and just press the button in the document editor:

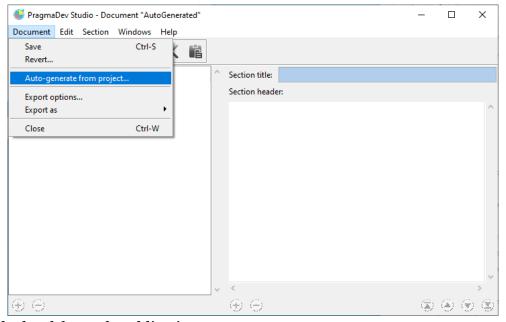




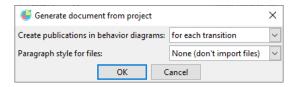
Please note it is also possible to automatically generate all publications and a document based on the project architecture. To do so, create a new document:



Open it and go to the "Document" / "Auto-generate from project..." menu:

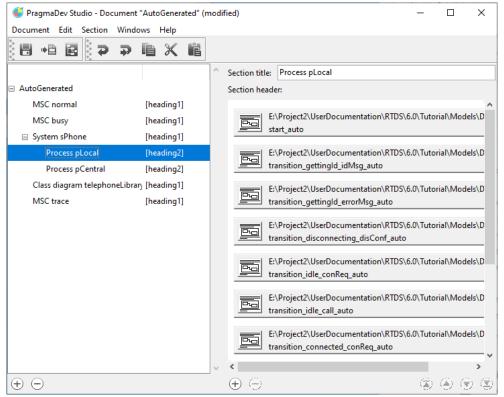


Select the level for each publication:





And a full document is generated:



If you already have existing publications at the proper level for the auto-generated document, they will be reused. If a publication is missing, it will be created. You can add explanation texts to the publications after creating the document.